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Streaming Bayesian Deep Tensor Factorization

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For ICML 2021



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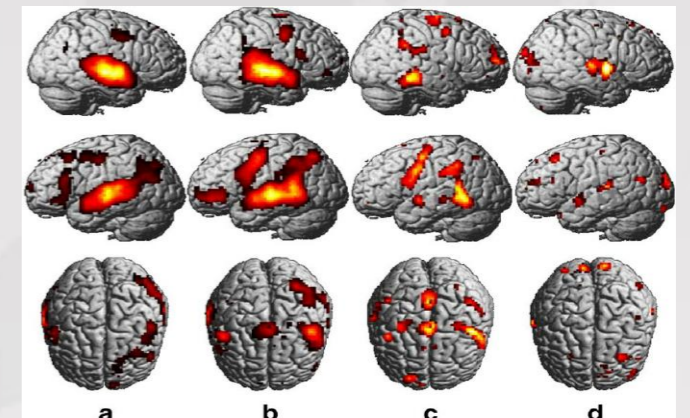
Tensor Data: Widely Used High-Order Data Structures to Represent Interactions of Multiple Objects/Entities



(user, movie, episode)



(user, advertisement, page-section)



(subject, voxel, electrode)



(user, item, online-store)



(user, user, location, message-type)



(patient, gene, condition)



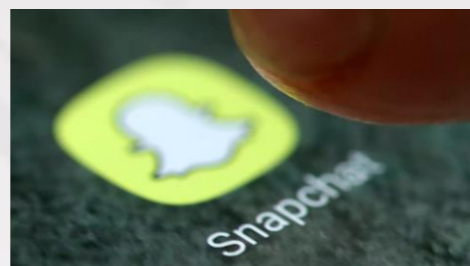
Tensor Decomposition

- Traditional methods: **Oversimplified multilinear assumptions**

$$\mathcal{Y}(i_1, i_2, i_3) = \sum_{j=1}^r \alpha_j \prod_k u_{i_k}^k \quad \text{Tucker}$$

$$\mathcal{Y} = \mathcal{W} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \times_3 \mathbf{U}_3 \quad \text{CP}$$

- Hard to handle fast **streaming** data!

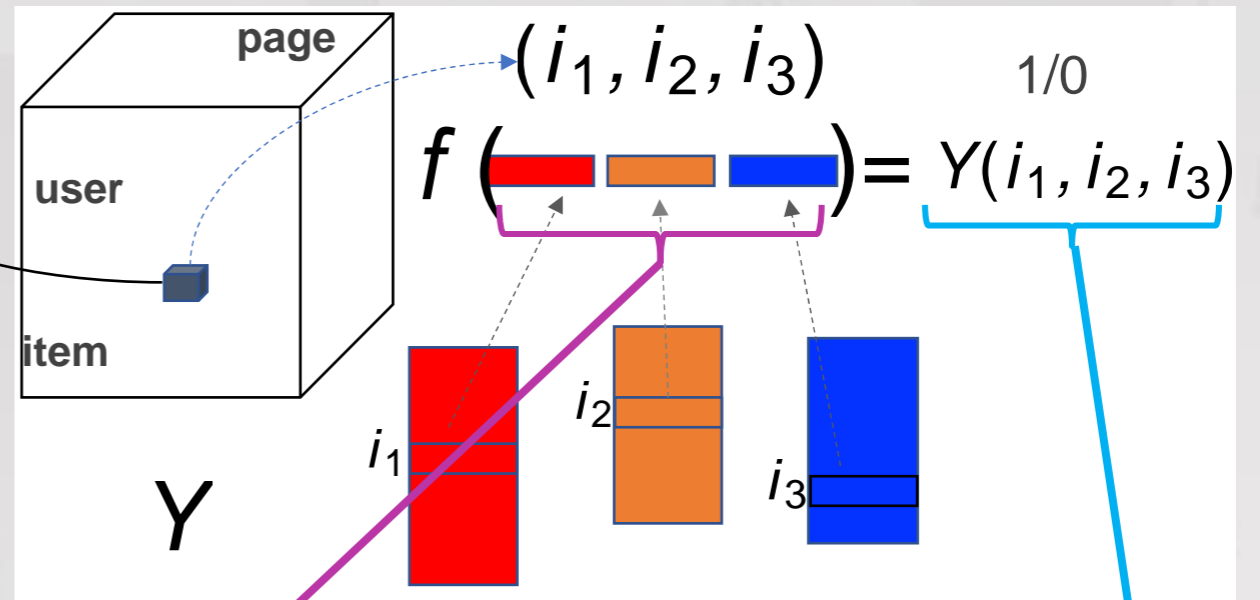


(privacy-demanding applications like Snapchat/Instagram, Data are **NOT** allowed to be stored/revisited)



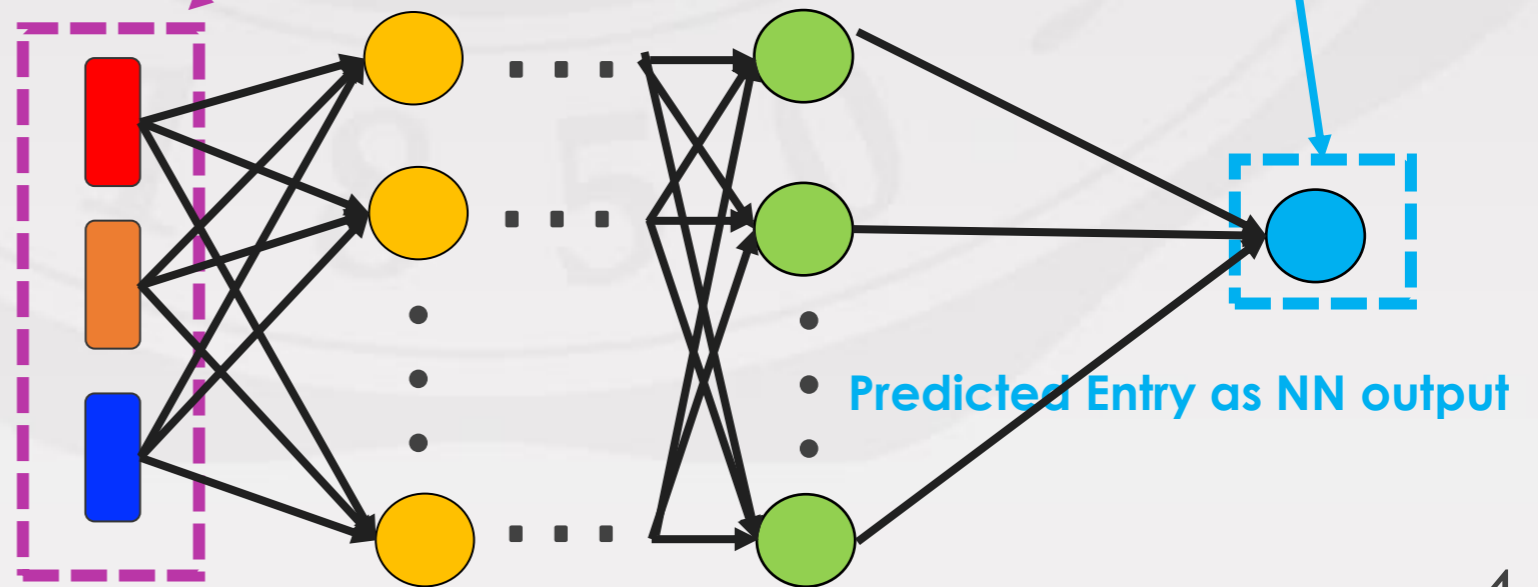
Interaction Records

user	item	page	purchase
100	25	35	1
23	21	56	0
100	25	35	1
..
32	33	46	0



Latent factors at each mode as NN input

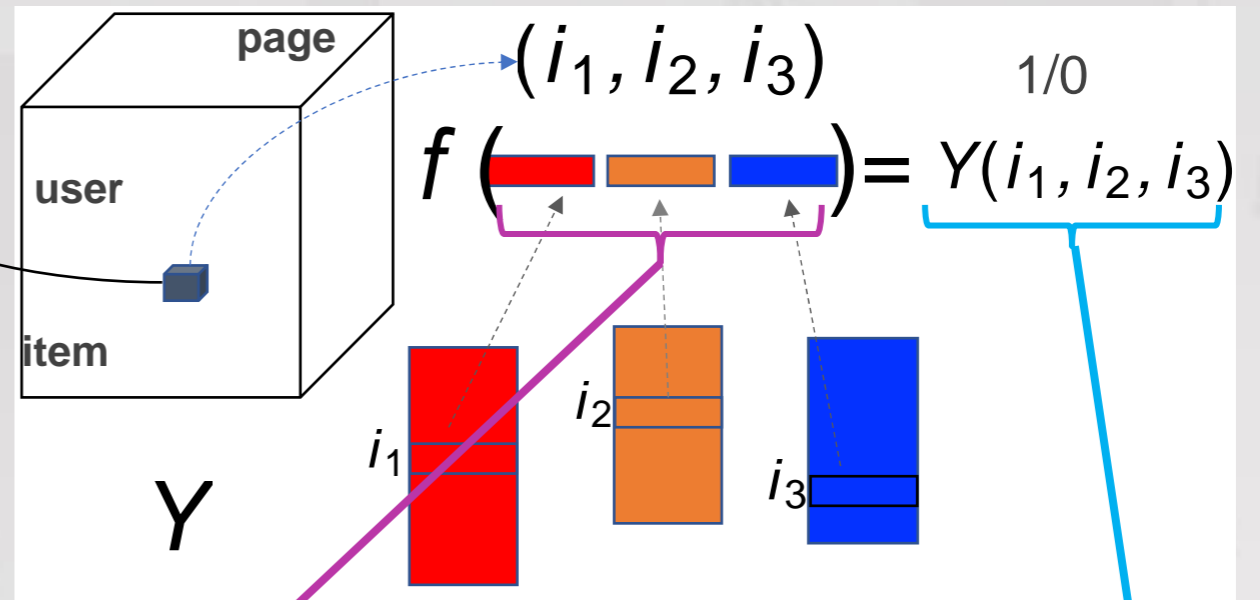
Problem: Overfitting Risk



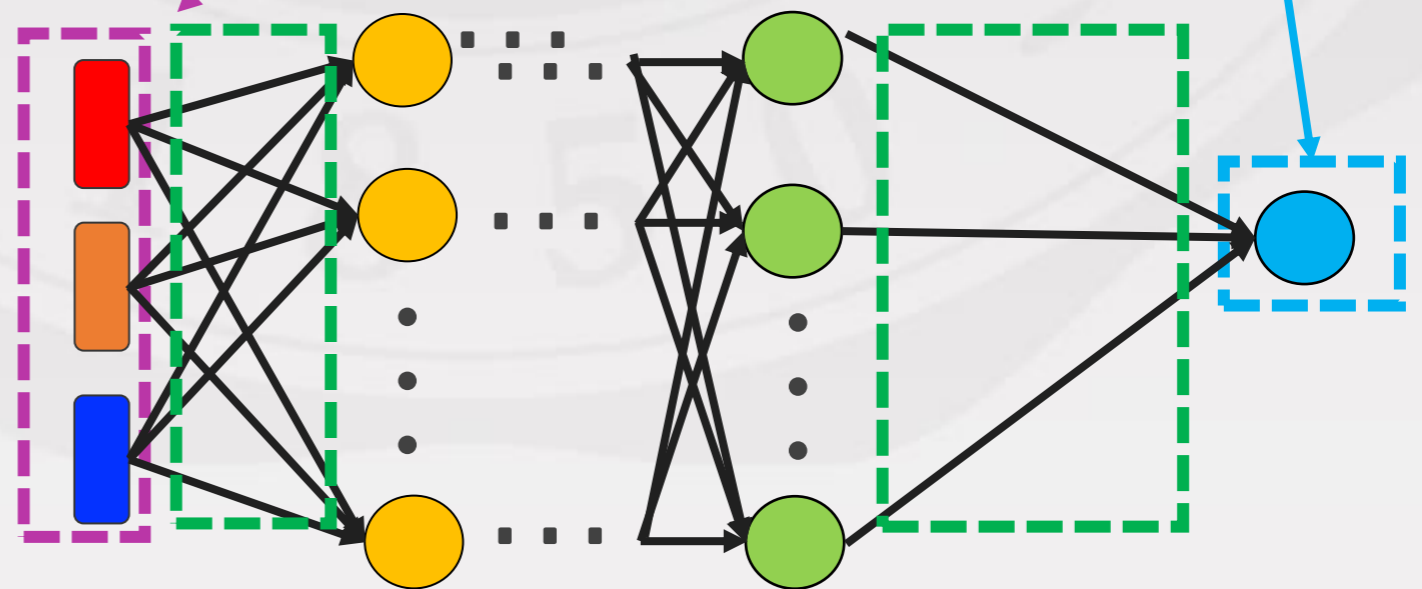


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Latent factors at each mode as NN input



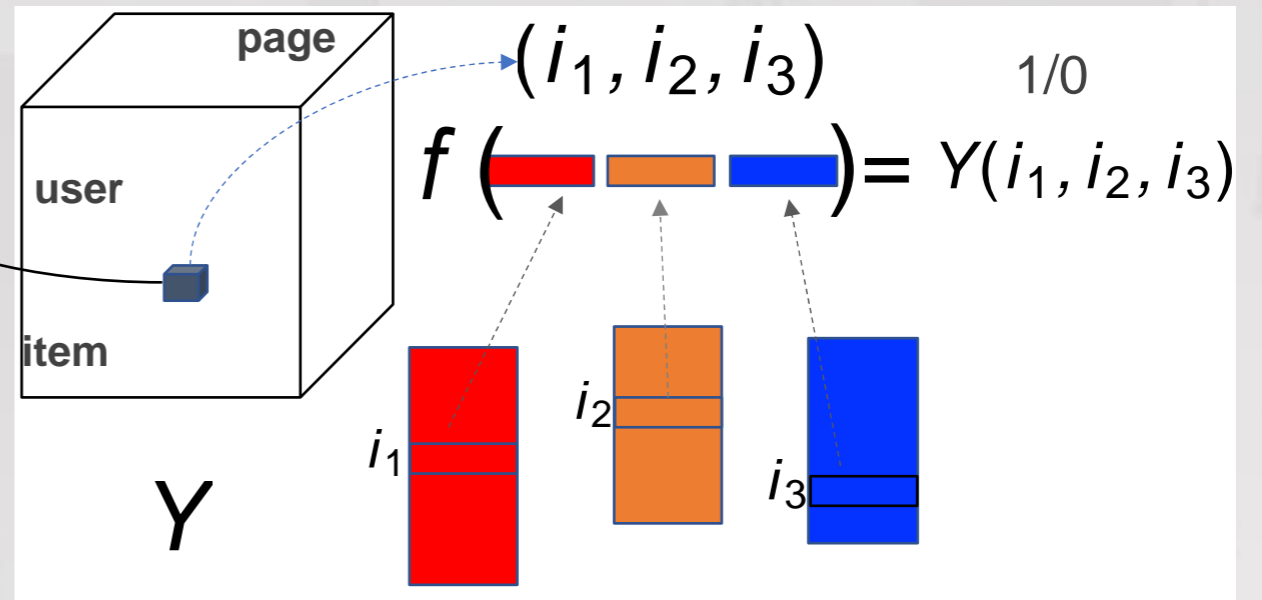
Predicted Entry as NN output

Assign spike & slab priors over each NN weights !



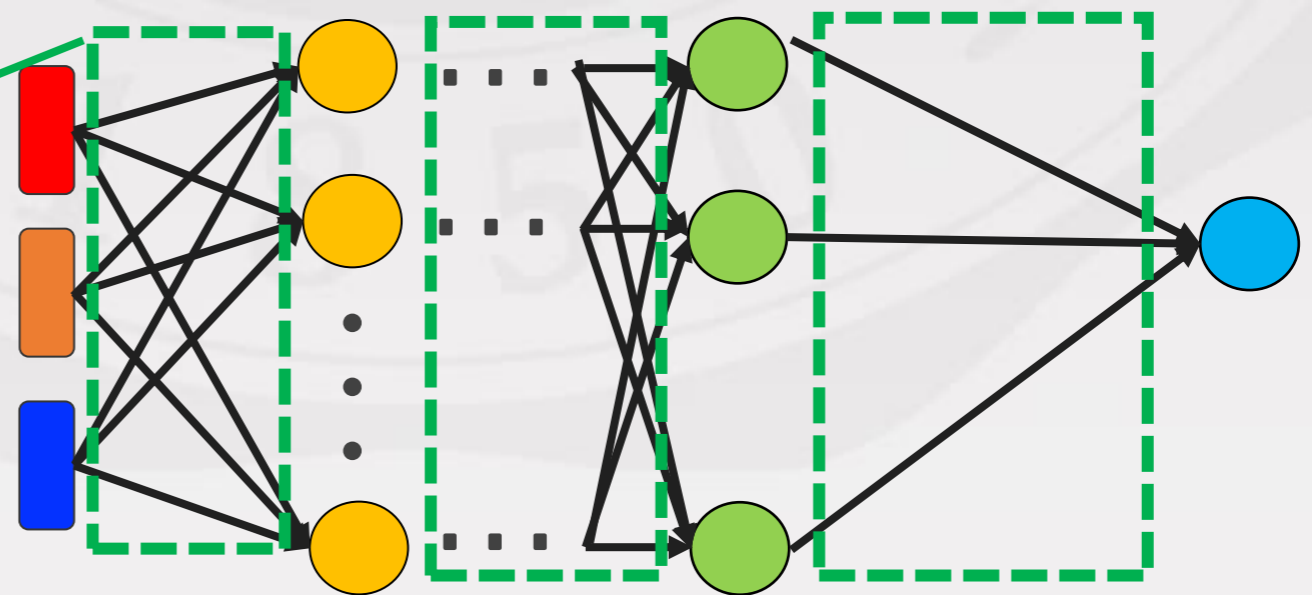
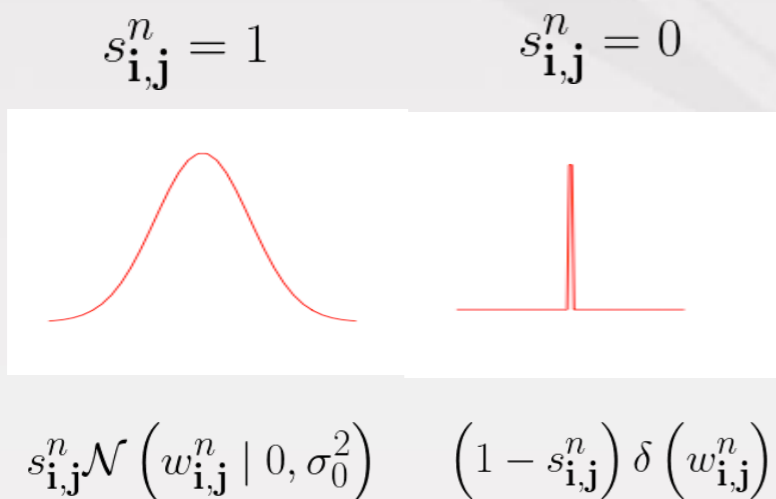
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Solution: Build a sparse BNN!

w_{ij}^n Assign spike & slab priors over each NN weights !





Online moment-match for Streaming inference

Classical ADF:

- streaming update for **BNN weights & involved factors**
- integrating entries one by one via **moment matching**

Closed form
Posterior update
(mean and var)

$$\left\{ \begin{array}{l} \mu^* = \mu + v \frac{\partial \log Z_n}{\partial \mu} \\ v^* = v - v^2 \left[\left(\frac{\partial \log Z_n}{\partial \mu} \right)^2 - 2 \frac{\partial \log Z_n}{\partial v} \right] \end{array} \right.$$

model evidence

intractable

$$Z_n = \int q_{\text{cur}}(\mathcal{W}, \mathcal{U}, \mathcal{S}) \Phi \left((2y_{\mathbf{i}_n} - 1) f_{\mathcal{W}}(\mathbf{x}_{\mathbf{i}_n}) \right) d\mathcal{W} d\mathcal{U} d\mathcal{S}$$



For tractable model evidence/analytic posterior update:

- we use **delta method**

I. Expand the BNN output at the mean of \mathbf{U} and \mathbf{W} (Taylor approx.)

$$f_{\mathcal{W}}(\mathbf{x}_{i_n}) \approx f_{\mathbb{E}[\mathcal{W}]}(\mathbb{E}[\mathbf{x}_{i_n}]) + \mathbf{g}_n^{\top} (\boldsymbol{\eta}_n - \mathbb{E}[\boldsymbol{\eta}_n])$$

Eliminate when take expectation

II. Get approx. of **first & second moments** of BNN output

$$\begin{aligned} \alpha_n &= \mathbb{E}_{q_{\text{cur}}}[f_{\mathcal{W}}(\mathbf{x}_{i_n})] \approx f_{\mathbb{E}[\mathcal{W}]}(\mathbb{E}[\mathbf{x}_{i_n}]) \\ \beta_n &= \text{Var}_{q_{\text{cur}}}(f_{\mathcal{W}}(\mathbf{x}_{i_n})) \approx \mathbf{g}_n^{\top} \text{diag}(\gamma_n) \mathbf{g}_n \end{aligned} \xrightarrow{\text{Moment matching}} q_{\text{cur}}(\cdot) = \mathcal{N}(\cdot | \alpha_n, \beta_n)$$

III. **Tractable** model evidence & **analytic form update** with ADF

$$\begin{aligned} Z_n &= \mathbb{E}_{q_{\text{cur}}(\mathcal{W}, \mathbf{U}, \mathcal{S})} [\Phi((2y_{i_n} - 1) f_{\mathcal{W}}(\mathbf{x}_{i_n}))] \\ &\approx \Phi\left(\frac{(2y_{i_n} - 1) \alpha_n}{\sqrt{1 + \beta_n}}\right) \end{aligned}$$



Spike & Slab priors: repeated approx. & refinement

- Approx. in exponential family: **Gaussian + Bernoulli**

$$\begin{aligned} p(w_{mjt} | s_{mjt}) &\propto A(w_{mjt}, s_{mjt}) \\ &= \text{Bern}(s_{mjt} | c(\rho_{mjt})) \mathcal{N}(w_{mjt} | \mu_{mjt}^0, v_{mjt}^0) \end{aligned}$$

Select posterior prob of each NN weight
<0.5: unselected <=> sparse

- Update with standard EP: analytic form
- Refine it after processing all entries in a coming batch to impose the **sparse inducing effect**



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Thanks for attention
Q&A time

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