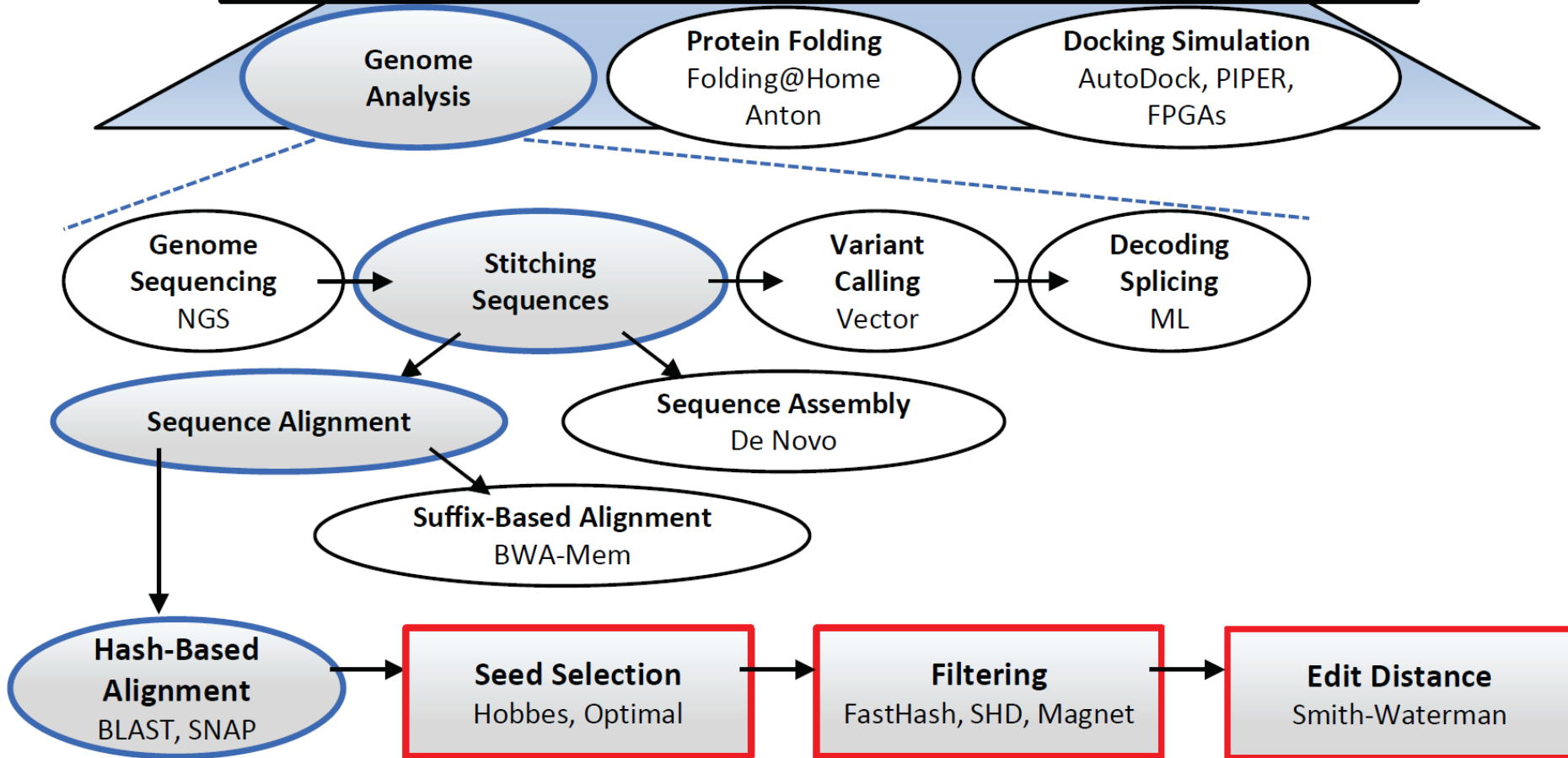


Lecture: Molecular Dynamics

- Topics: sequence alignment wrap-up, Anton for moldyn

Precision Medicine

Applications: cancer treatments, newborn screening, rare diseases, biohazard detection, etc.



Burrows-Wheeler Transform

A data transformation that is reversible and amenable to compression

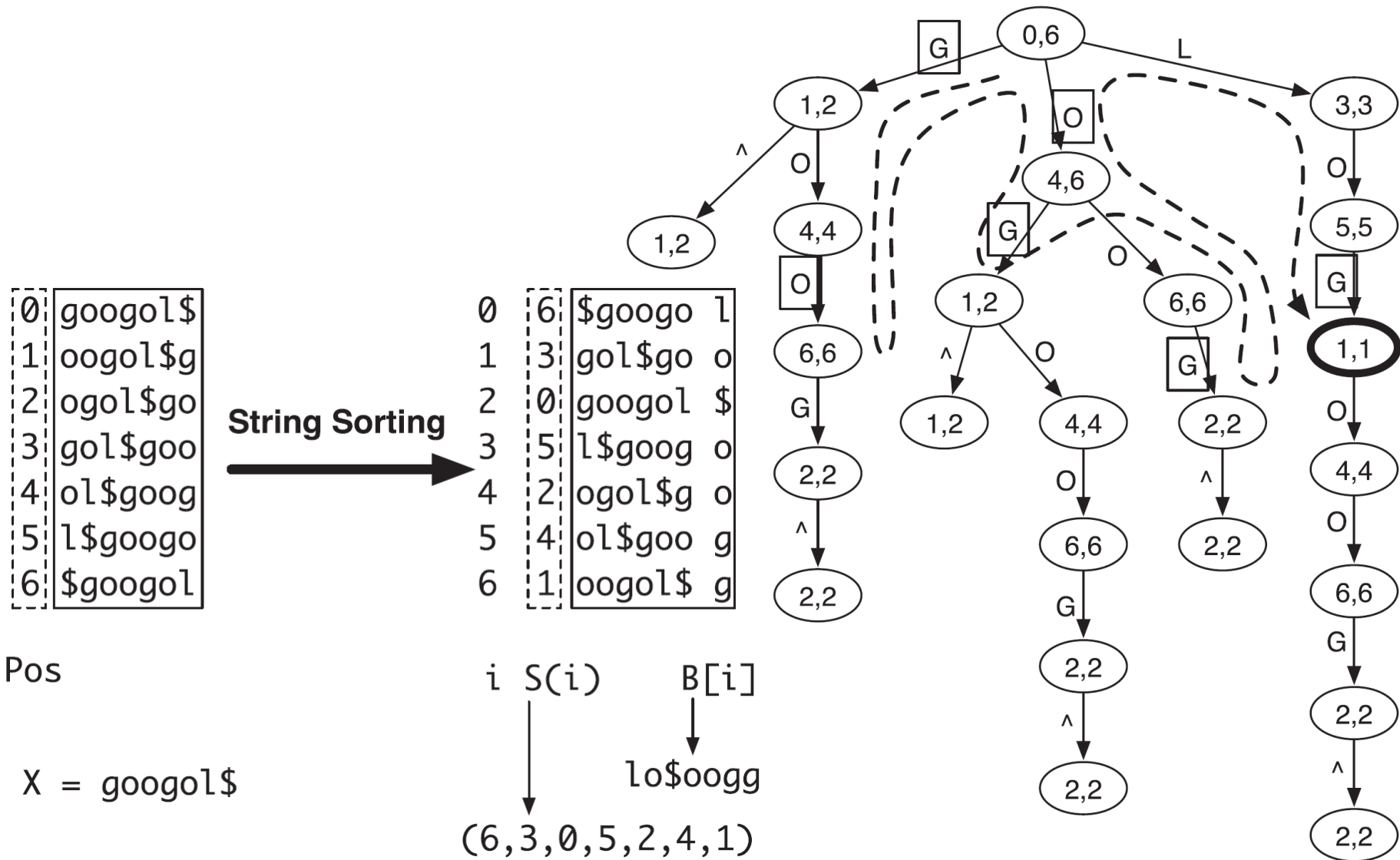
Transformation

Input	All rotations	Sorted into lexical order	Taking last column	Output last column
^BANANA	^BANANA	ANANA ^B	ANANA ^B	BNN^AA A
	^BANANA	ANA ^BAN	ANA ^BAN	
	A ^BANAN	A ^BANAN	A ^BANAN	
	NA ^BANA	B ANANA ^	BANANA ^	
	ANA ^BAN	NANA ^BA	NANA ^BA	
	NANA ^BA	NA ^BANA	NA ^BANA	
	ANANA ^B	^BANANA	^BANANA	
	BANANA ^	^BANANA	^BANANA	

When applied to text, you'll see many consecutive occurrences as below. Note that the last column is highly compressible.

he dog ... T
 he object ... T

BWT Applied to Sequence Alignment



Burrows Wheeler Alignment

- The trie structure reduces the storage requirement; strings with common suffixes share a portion of the trie
- Because the strings are sorted, each node must only store two numbers to capture the many possible matching locations
- In addition to the above “compression”, the many matching locations are determined in $O(w)$ time, where w is the string length; this is true for perfect matches (see example for GO on previous slide)
- For approximate matches, you may have to navigate a significant portion of the trie (see example for LOL on previous slide)
- Note that memory access pattern is quite random, but capacity is low

Molecular Interactions

- DNA and RNA eventually produce the protein (a sequence of amino acids) – these proteins fold into a particular 3D structure that determines their behavior – gene mutations result in potentially incorrect protein expressions that can result in functionally incorrect folds
- Drug delivery – does it bind to carriers in the blood – does it bind to the appropriate receptors

Anton

- Research supercomputer by DE Shaw Research to accelerate molecular dynamics simulations; Anton in 2008; Anton 2 in 2013; a “microscope” for biochemistry; specialization before it was cost-effective



Scale of Mol Dyn

- Simulations are performed in time steps; each time step is a few femto-seconds (10^{-15} seconds)
- Interesting interactions happen at the scale of milli-seconds; must therefore simulate 10^{12} steps
- Anton introduces a 1000x speedup, enabling milli-second simulations in a couple of months
- Anton 2 introduces an additional 5x speedup
- 42 kW/rack; 190 W Anton 2 chip; 408 mm² chip

Anton Goals

- Trying to do one step involving 10s of thousands of atoms in 1000s of cycles
- New hardware, new algorithms for higher parallelism and lower inter- and intra-chip communication
- Low latency compute and communication
- Can't use speculation because each step depends on the previous step
- Related: Folding@home explores many parallel trajectories on very short time scales

Biochem Background

- Modeling a small (repeating) volume of protein, solvent, and other chemicals
- Two significant steps: force calculation and integration; integration applies Newton's laws and is also non-trivial
- Forces are of two types: bonded and non-bonded
- Bonded: force between an atom and other atoms that share a covalent bond – an atom is typically bonded to <4 atoms, so calculating these forces takes linear time
- Non-bonded forces: van der Waals and electrostatic

Biochem Background

- Non-bonded forces are the bottleneck because there are a quadratic number of interactions
- van der Waals: weak forces among atoms because of varying electron positions within the atom; these are weak enough that we can ignore them beyond a cutoff radius
- Electrostatic forces cannot be ignored, but we can approximate some of the long-range interactions
- Within a small radius, the pairwise interactions (vdw and es) are calculated; at long-range, they use FFT-based techniques to compute the es forces (charges are mapped to a mesh)

Parallelization

- The space is partitioned into smaller boxes; each computational “node” is responsible for its home box
- They use a “neutral territory (NT)” method where a node computes close-range interactions for its home box and parts of two neighboring boxes
- The particles in a node are split into “tower” (home box and one neighbor box) and “plate” (home box and the other neighbor box) groups; every element of tower is interacted with every element of plate
- This is the key step that requires the most time and hw

Amdahl's Law Analysis

- Must target everything to get 1000x

Table 1. Profile of a single-processor run using the GROMACS MD package [33].

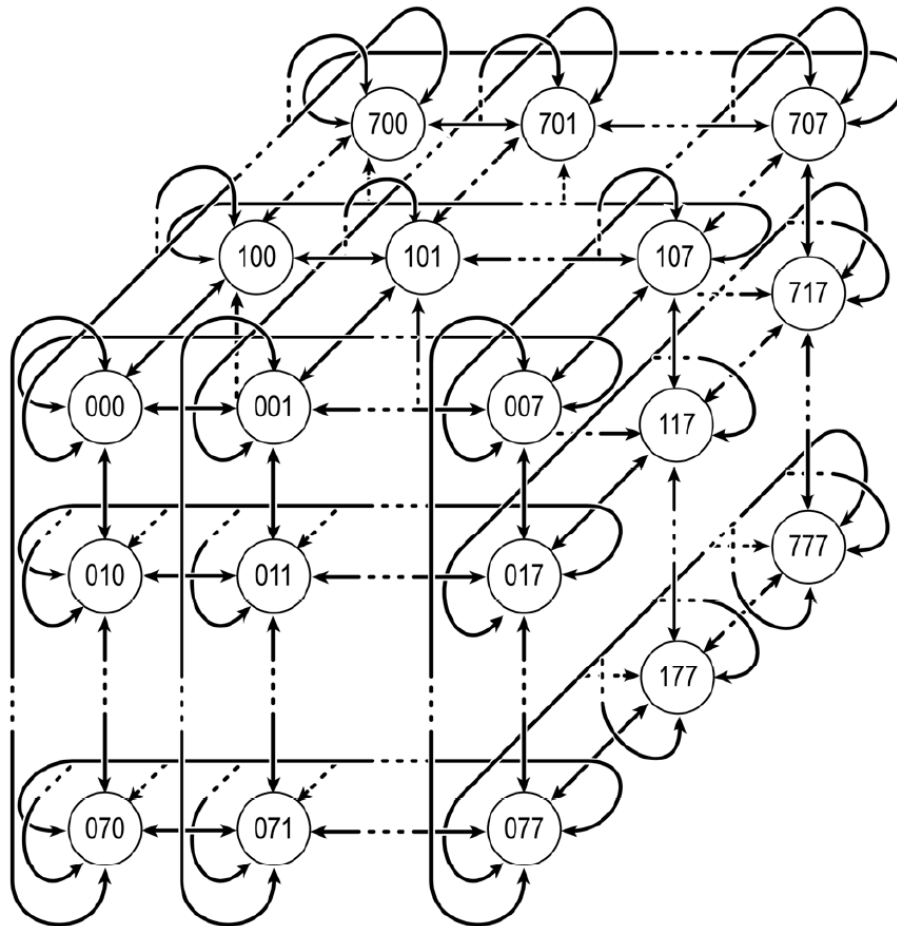
Phase	Task	% execution time
Force Calculation	Explicit pairwise nonbonded interactions	60
	FFT, inverse FFT, & Fourier space multiplication	17
	Charge spreading and force interpolation	13
	Bonded force terms	1
	Correction force terms	4
Integration	Position & velocity updates	2
	Constraints	2
	Pressure computation	1

Contributions

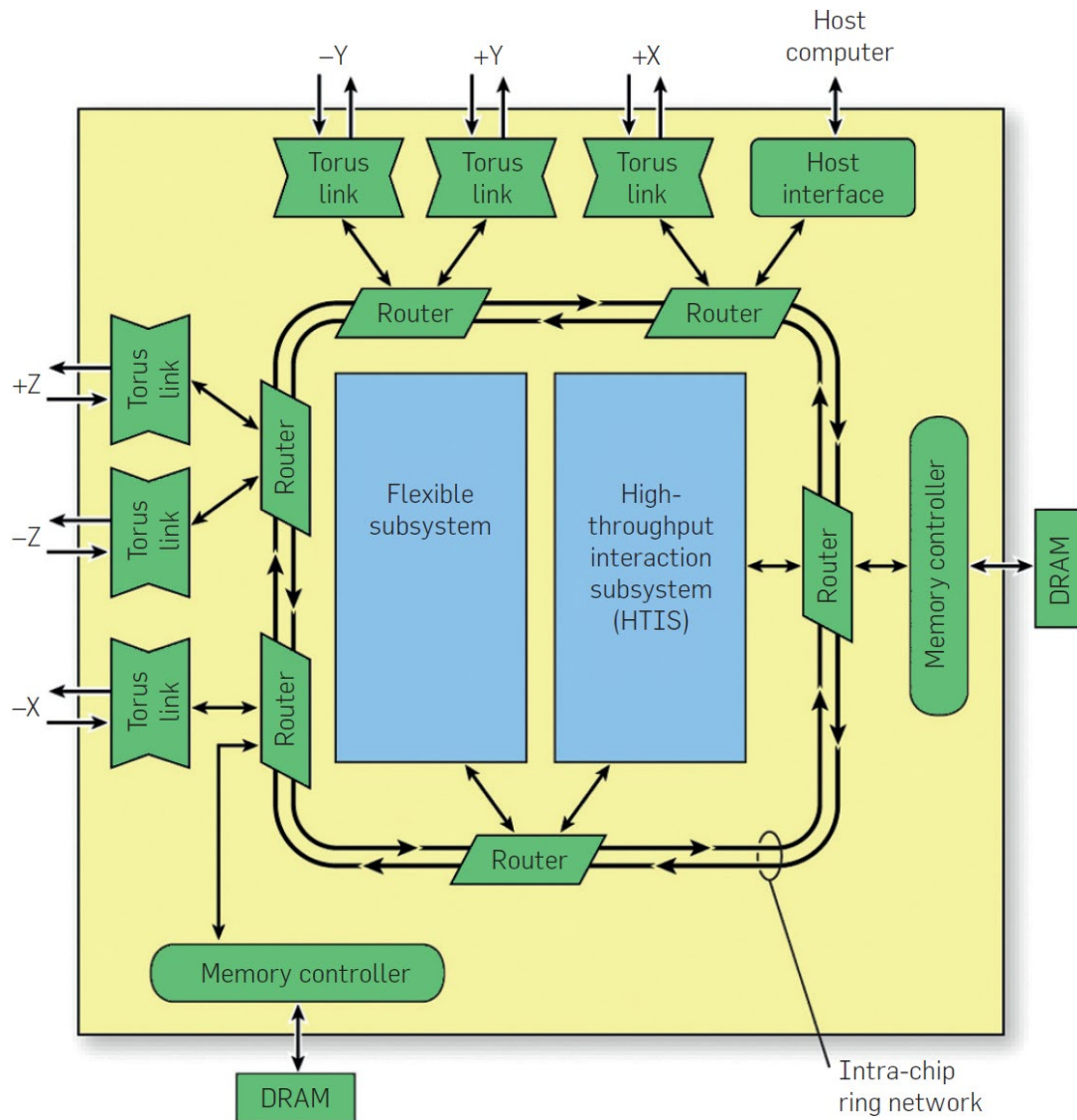
- Specialized pipeline for non-bonded nearby interactions
- Programmable processor with custom ISA for all other operations
- Accumulation at the memory system; little on-chip storage
- Network support for m-cast and compressed sparse packets
- Synchronization and push-based communication

Architecture

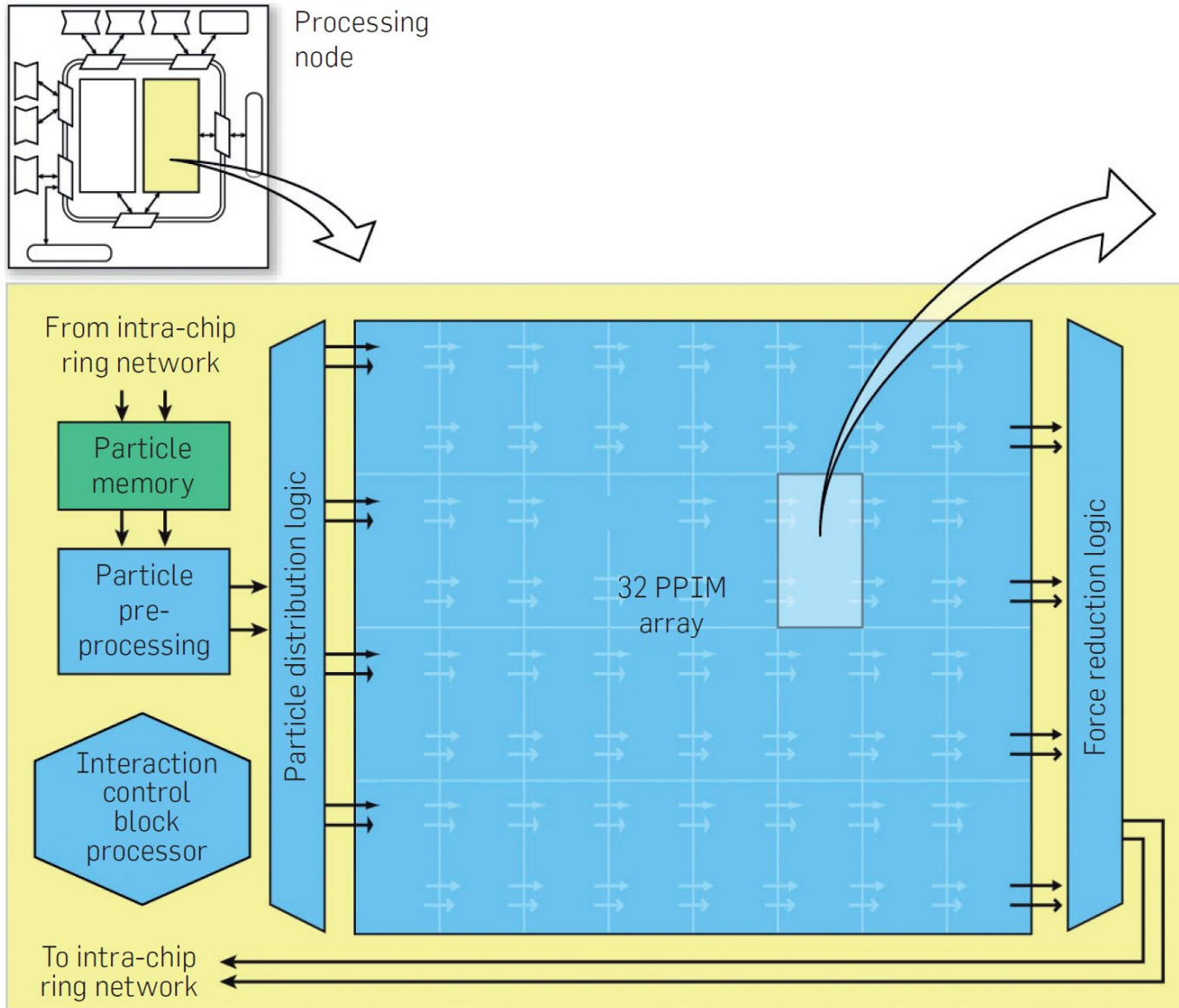
- 512-node torus; a node has a chip, attached DRAM, and 6 ports;
4 nodes per board; 32 boards per rack; 4 racks



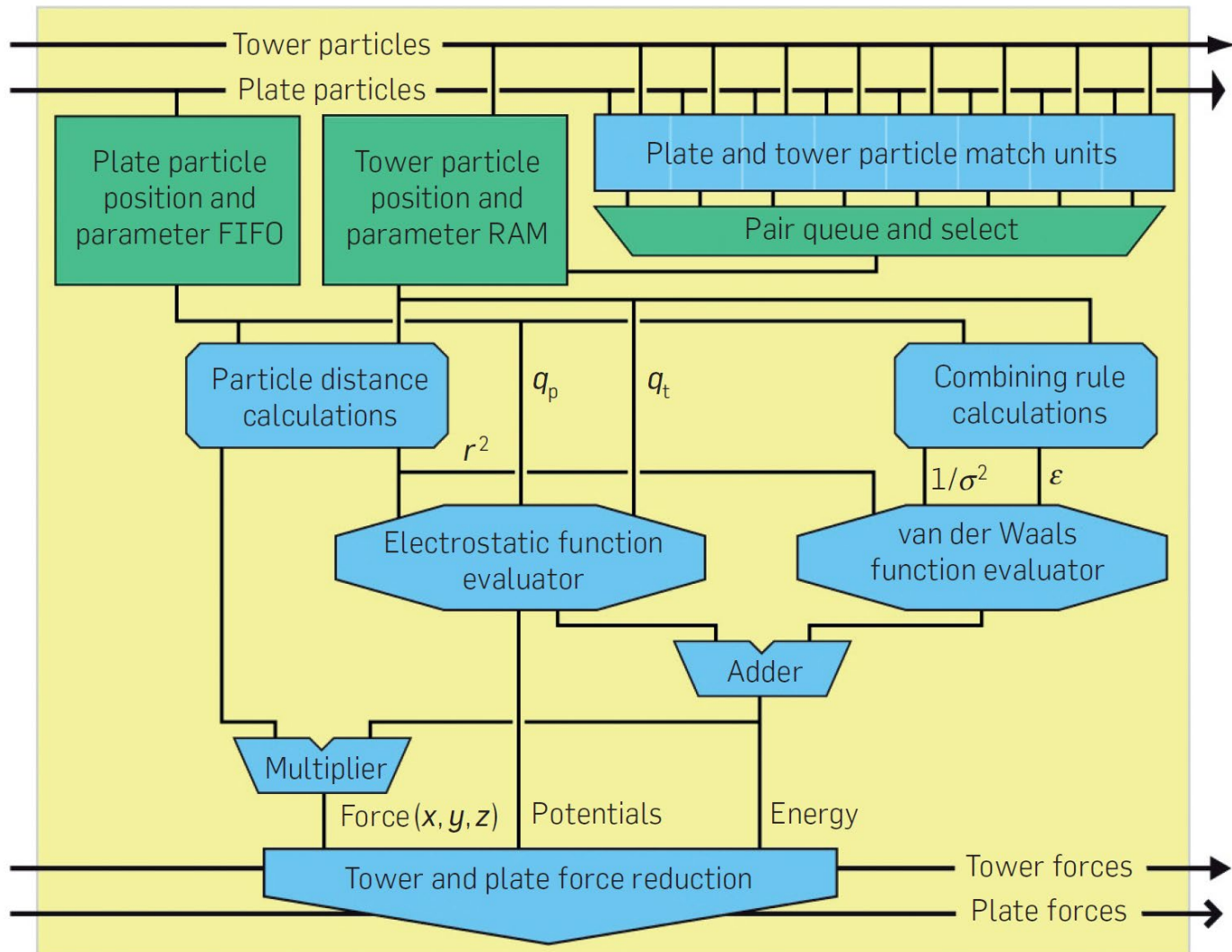
Anton Chip



HTIS – Hi-Throughput Interaction Subsystem



HTIS – Hi-Throughput Interaction Subsystem

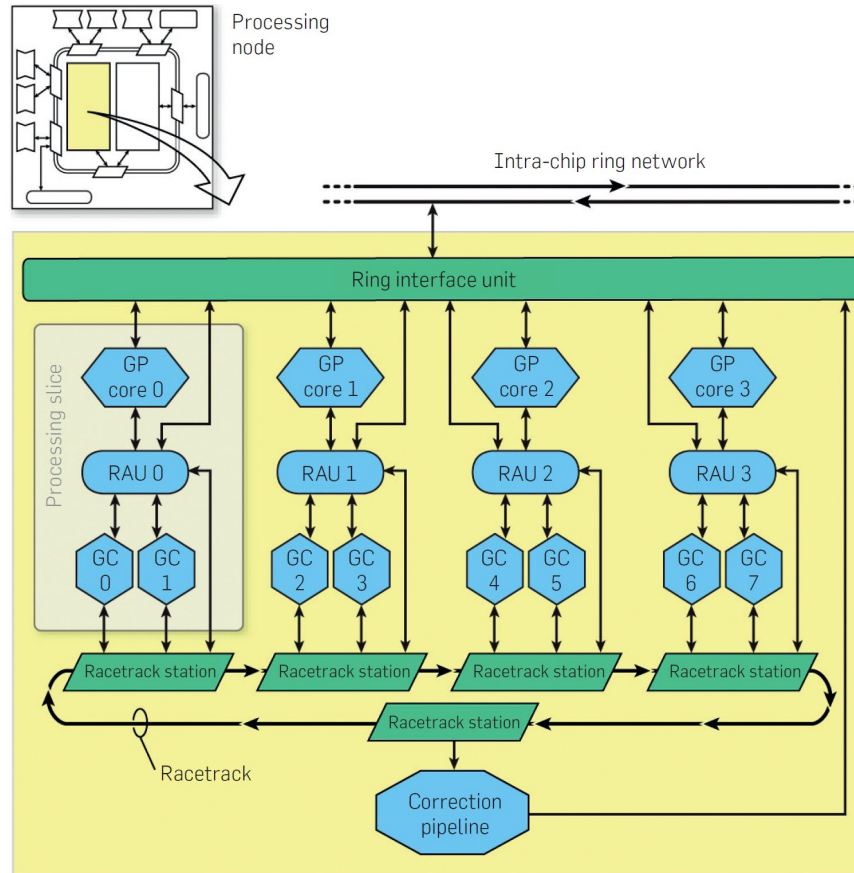


HTIS – Hi-Throughput Interaction Subsystem

- Particles are received through push-communication from neighbors
- ICB buffers these and controls the systolic array computations
- 32 PPIMs store parts of the tower particles; the plates are replicated four times and are streamed to each of the rows
- At each step, 8 matches are performed to identify the pairs that must be processed; these are then sent thru the rest of the pipeline
- 26-stage PPIM pipeline at 800 MHz; rest of the chip operates at 400 MHz; the pipeline is fixed-function and uses variable precision
- Each PPIM stores the forces collected for the tower; the plates carry their forces as they move to the right; the forces from the four rows are merged at the end and sent to the appropriate buffers; at the end, the tower forces are streamed out as well
- DRAM is only used when spilling very large simulations; on-chip cache is enough to handle most working sets

Flexible Subsystem

- Responsible for several complex operations; the GP cores handle control flow; the remote access units have scratchpads and take care of data movement; the geometry cores take care of SIMD calculations; the racetrack is used for intra-node communication



Speedups

Task	Anton 512-node speedup over GROMACS	Divided by 512 (single-node speedup)
Range-limited non-bonded forces	50,000	98.5
Charge spreading and force interpolation	5,400	10.5
FFT and Fourier space multiplication	3,700	7.2
Bond forces	4,600	9.0
Correction forces	3,700	7.2
Position and velocity updates	1,200	2.4
Constraint calculations	1,400	2.7
Temperature computation	400	0.8
Total	9,000	17.6

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Anton 2

	ANTON	ANTON2
CPU cores	13	66
CPU clock	485 MHz	1,650 MHz
Interaction pipelines	66	152
Pipeline clock	970 MHz	1,650 MHz
Peak throughput*	2.73 TFXOPS	12.7 TFXOPS
Main SRAM	128 KB	4,096 KB
Atoms/ASIC	460	8,000
Channel B/W	607 Gb/s	2.7 Tb/s

Power: 75 W 190 W
Size: 300 mm² 408 mm²

The Molecular Dynamics Computation

1. Divide time into uniform timesteps (~ 1 fs)
2. Compute forces on all particles in system in a timestep

$$E = \begin{array}{ll} \text{Bonded:} & \text{(Flexible Subsystem)} \\ \Sigma k_b(r-r_0)^2 & \text{Stretch} \\ + \Sigma k_\theta(\theta-\theta_0)^2 & \text{Bend} \\ + \Sigma A[1+\cos(n\pi-\phi)] & \text{Torsion} \end{array}$$

$$\begin{array}{ll} \text{Non-Bonded:} & \text{(High Throughput Interaction Subsystem)} \\ + \Sigma \Sigma q_i q_j / r_{ij} & \text{Electrostatic} \\ + \Sigma \Sigma q_i q_j / r_{ij} & \text{Van der Waals} \end{array}$$

3. Based on these forces, compute new velocities and positions for all particles

$$V = V_0 + F * \Delta T / M \quad \text{(Flexible Subsystem)}$$

$$S = S_0 + V_0 * \Delta T + F * (\Delta T)^2 / M$$

4. Rinse and repeat... About 1 TRILLION times to simulate a millisecond!

Also, do a bunch of ugly housekeeping functions along the way to maintain (as needed for experiment) constant temperature and / or pressure, etc.

References

- Anton papers and presentations at: ISCA'07, HotChips'08, SC'09
- Anton 2 papers at: HotChips'14, SC'14

Title

- Bullet