Lecture 26: Multiprocessors

- Today's topics:
 - Snooping-based coherence
 - Synchronization
 - Consistency

Example

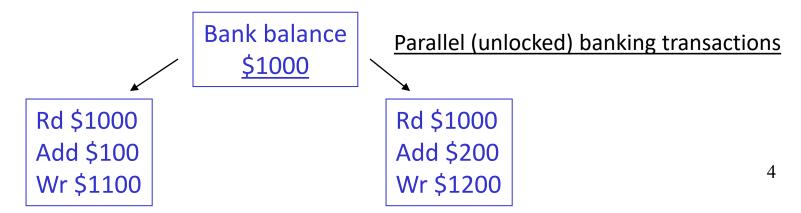
Request	Cache Hit/Miss	Request on the bus	Who responds	State in Cache 1	State in Cache 2	State in Cache 3	State in Cache 4
				Inv	Inv	Inv	Inv
P1: Rd X	Miss	Rd X	Memory	S	Inv	Inv	Inv
P2: Rd X	Miss	Rd X	Memory	S	S	Inv	Inv
P2: Wr X	Perms Miss	Upgrade X	No response. Other caches invalidate.	Inv	M	Inv	Inv
P3: Wr X	Write Miss	Wr X	P2 responds	Inv	Inv	M	Inv
P3: Rd X	Read Hit	-	-	Inv	Inv	M	Inv
P4: Rd X	Read Miss	Rd X	P3 responds. Mem wrtbk	Inv	Inv	S	S

Cache Coherence Protocols

- Directory-based: A single location (directory) keeps track of the sharing status of a block of memory
- Snooping: Every cache block is accompanied by the sharing status of that block – all cache controllers monitor the shared bus so they can update the sharing status of the block, if necessary
- Write-invalidate: a processor gains exclusive access of a block before writing by invalidating all other copies
- Write-update: when a processor writes, it updates other shared copies of that block

Constructing Locks

- Applications have phases (consisting of many instructions) that must be executed atomically, without other parallel processes modifying the data
- A lock surrounding the data/code ensures that only one program can be in a critical section at a time
- The hardware must provide some basic primitives that allow us to construct locks with different properties



Synchronization

- The simplest hardware primitive that greatly facilitates synchronization implementations (locks, barriers, etc.) is an atomic read-modify-write
- Atomic exchange: swap contents of register and memory
- Special case of atomic exchange: test & set: transfer memory location into register and write 1 into memory (if memory has 0, lock is free)
- lock: t&s register, location bnz register, lock CS

location, #0

When multiple parallel threads execute this code, only one will be able to enter CS

Coherence Vs. Consistency

- Coherence guarantees (i) write propagation

 (a write will eventually be seen by other processors), and
 (ii) write serialization (all processors see writes to the same location in the same order)
- The consistency model defines the ordering of writes and reads to different memory locations – the hardware guarantees a certain consistency model and the programmer attempts to write correct programs with those assumptions

Consistency Example

Consider a multiprocessor with bus-based snooping cache coherence

```
Initially A = B = 0
P1
P2
A \leftarrow 1
B \leftarrow 1
...
if (B == 0) if (A == 0)
Crit.Section
```

Consistency Example

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```

The programmer expected the above code to implement a lock – because of ooo, both processors can enter the critical section

Sequential Consistency

- A multiprocessor is sequentially consistent if the result of the execution is achieveable by maintaining program order within a processor and interleaving accesses by different processors in an arbitrary fashion
- The multiprocessor in the previous example is not sequentially consistent
- Can implement sequential consistency by requiring the following: program order, write serialization, everyone has seen an update before a value is read – very intuitive for the programmer, but extremely slow

Relaxed Consistency

- Sequential consistency is very slow
- The programming complications/surprises are caused when the program has race conditions (two threads dealing with same data and at least one of the threads is modifying the data)
- If programmers are disciplined and enforce mutual exclusion when dealing with shared data, we can allow some re-orderings and higher performance
- This is effective at balancing performance & programming effort