MLIR for Fortran

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* Disclaimer: opinions in this talk are those of the presenter, and do not reflect the official opinions of IBM!

Overview

- New research project planned for 2020 across Georgia Tech, U.Alberta, IBM
- Motivated by past work at IBM on ASTI optimizer for Fortran, and recent MLIR work at IBM with U.Alberta
- Goal is to leverage past experiences with ASTI's High-level Intermediate Representation (HIR) to evaluate the design space for an MLIR dialect for optimization of Fortran codes
 - Special focus on array statements, loops, array accesses
 - Such an MLIR dialect could be useful for optimization of HPC codes in other languages as well
- Complementary to ECP Flang project
- All feedback and suggestions are most welcome!

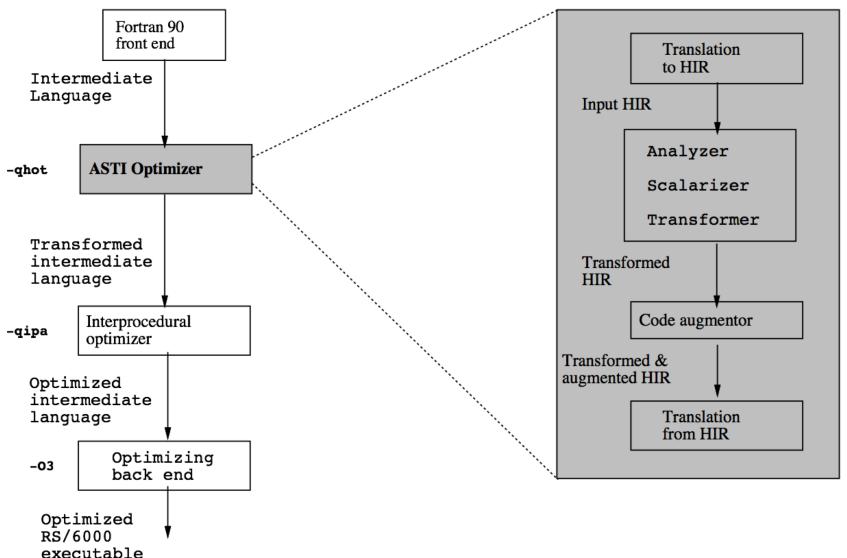
Background: ASTI Optimizer

(Analyzer, Scalarizer, Transformer, Interprocedural optimizer)

- Automatic selection of high-order transformations in the IBM XL Fortran compilers
- Quantitative approach to program optimization using cost models
- High-order transformations selected for uniprocessor target include: loop distribution, fusion, interchange, reversal, skewing, tiling, unrolling, and scalar replacement of array references
- Design and initial product implementation completed during 1991–1993

Reference: "Automatic Selection of High Order Transformations in the IBM XL Fortran Compilers", V. Sarkar, IBM Journal of Res. & Dev., Vol. 41, No. 3, May 1997.

Structure of XL Fortran Product Compiler (Version 4)



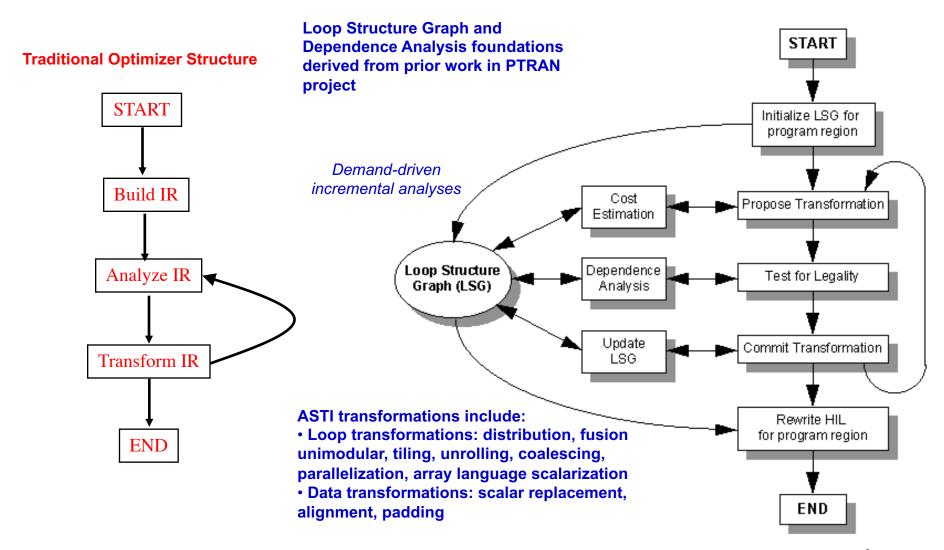
```
(a) Example loop containing an array assignment statem
_____
do k = 1, n
  A(1:n,1:n) = A(1:n,1:n) + spread(B(1:n,k),2,n) *
                          spread(C(k,1:n),1,n)
end do
(b) After unoptimized scalarization:
_____
do k = 1. n
  do i1 = 1, n ! parallelizable loop
     T1(i1) = B(i1.k)
  end do
  do i2 = 1, n ! parallelizable loop
     do i1 = 1, n ! parallelizable loop
        T2(i1,i2) = T1(i1)
     end do
  end do
  do i1 = 1, n ! parallelizable loop
     T3(i1) = C(k,i1)
  end do
  do i2 = 1, n ! parallelizable loop
     do i1 = 1, n ! parallelizable loop
        T4(i1,i2) = T3(i2)
     end do
  end do
  do i2 = 1, n ! parallelizable loop
     do i1 = 1, n  ! parallelizable loop
        T5(i1,i2) = A(i1,i2) + T2(i1,i2) * T4(i1,i2)
     end do
  end do
  do i2 = 1, n ! parallelizable loop
     do i1 = 1, n ! parallelizable loop
       A(i1,i2) = T5(i1,i2)
     end do
  end do
end do
```

Scalarization example

```
(c) After optimized scalarization:
do k = 1, n
  do i2 = 1, n ! parallelizable loop
     do i1 = 1, n  ! parallelizable loop
        A(i1,i2) = A(i1,i2) + B(i1,k) * C(k,i2)
     end do
  end do
end do
(d) After collective transformation of loop nest (c):
 ._____
do bb$_i2=1,n,b$_i2   ! parallelizable loop
  do bb$_i1=1,n,b$_i1 ! parallelizable loop
     do bb_k = 1, n, b_k
        do i2=max(1,bb$_i2),min(n,bb$_i2+b$_i2-1)
           do i1=max(1,bb$_i1),min(n,bb$_i1+b$_i1-1)
              do k=max(1,bb\$_k),min(n,bb\$_k+b\$_k-1),1
                 A(i1,i2) = A(i1,i2) + B(i1,k) * C(k,i2)
              end do
           end do
        end do
     end do
  end do
                                            5
end do
```

Structure of ASTI Transformer

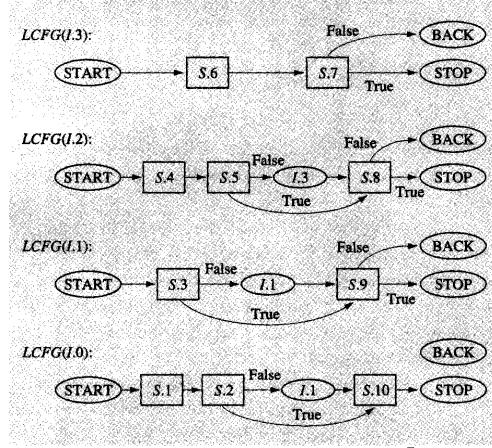
[LCPC 1991, PLDI 1992, CASCON 1994, ICPP 1995, IBM JRD 1997, ICPP 1997, SPAA 1997, LCR 1998, LCPC 1998, ISPASS 2000, ICS 2000, IJPP 2001]



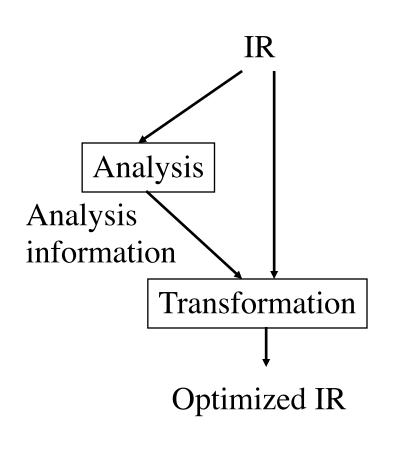
Loop Structure Tree

S.1 S.2 /1 S.10 S.3 1/2 S.9 S.4 S.5 1/3 S.8

Loop-Level Control Flow Graphs



Structure of a Single Optimization Pass



Examples:

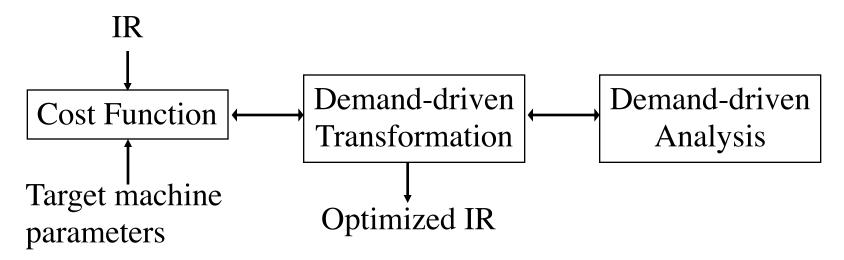
Analysis	Transformation
Value	Common
numbering	subexpression
	elimination
Liveness	Dead store
analysis	elimination
Dependence	Instruction
analysis	scheduling

Issues

- **Heuristics:** sequence of optimization passes for a given optimization level is usually hardwired
- **Phase ordering:** a later optimization can create new opportunities for a previous optimization
- Compile time/space overheads: all optimization passes are performed on all instructions in all procedures
- Unpredictability: hard to predict how much performance improvement will be delivered by compiler optimizations
- **Pessimization:** optimizing transformations can sometimes degrade performance

Rethinking compilers ... a quantitative approach

Optimization = Cost function + Analysis + Transformation



Examples:

Cost Function	Analysis	Transformation
Store freqs	Live variable analysis	Dead store elimination
Basic block freqs	Bounds analysis	Bounds check elimination
Cache misses	Dependence vectors	Loop interchange and tiling

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Transformations performed in ASTI for Locality Optimizations

- 1. Initialization
- 2. Loop distribution
- 3. Identification of perfect loop nests
- 4. Reduction recognition
- 5. Locality optimization
- 6. Loop fusion
- 7. Loop-invariant scalar replacement
- 8. Loop unrolling and interleaving
- 9. Local scalar replacement
- 10. Transcription generate transformed HIR

Other transformations performed for Vector/SMP/HPF parallelization

Challenges

- Cost function should be efficient to compute but sufficiently accurate
 - Use *lower and upper bounds* as approximations
- Well-tuned code should not incur large compilation overhead
 - Perform analysis and transformation incrementally and on demand, only when cost function indicates potential for performance improvement
 - Use algorithms with low-polynomial-time complexity
- Phase ordering should be driven by cost functions
 - Use classical optimization theory heuristics in driver for optimizing compiler e.g., sort potential transformations in decreasing order of benefit

Summary

- Time to rethink optimizing compilers
 - Reduce compilation overhead
 - Increase optimization effectiveness
- Quantitative approach provides a promising foundation
- *Future goal:* build an optimizer in which all optimization selection and phase ordering decisions are driven by cost functions rather than hardwired heuristics
 - MLIR offers a promising opportunity for such an approach
 - Fortran is an important domain for demonstrating such an approach

BACKUP SLIDES START HERE

