

# Compressed Sensing and OMP

Note Title

3/23/2016

## Least Squares Regression

observations  $\downarrow$   
 $n \geq d$   $\leftarrow$  variables

$$A x \approx b \implies \arg \min_x \|Ax - b\|_2^2$$

$n \times d$   $\uparrow$   $n \times 1$   
 $x$  unknown  $d \times 1$

$$x = (A^T A)^{-1} A^T b$$

sparse  $\swarrow$  if  $d > n \implies$  many solutions to  $x$  with 0 error

## Compressed Sensing

$m \ll n$  non-zeros in  $x$

(Tao-Candes) (Donoho) 2004

(model  $x$ )  $S \leftarrow$  signal, sparse  $|S| = d$

$\neq$  non-zero  $s$

$$S = [0, 1, 0, 0, 0, 1, 0, 0, \dots, 0, 0]$$

Measurement matrix  $X$  entries  $X_{ij} \in \{-1, 0, +1\}$

integers  $m \times d$

$$y = X S^T \leftarrow$$
 actual measurements  $m \times 1$

$m \ll d \implies$  Recover  $S$  exactly

measurement row  $X_i$

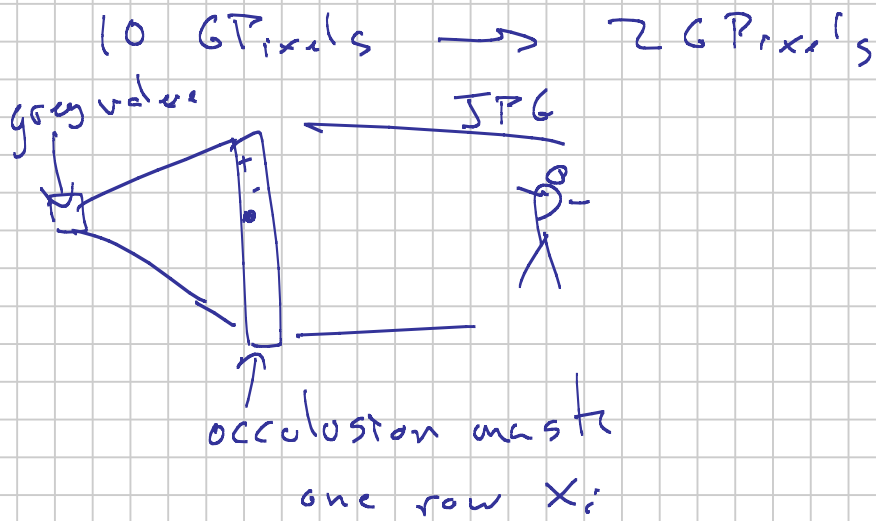
$$X_i = [1, -1, 0, 0, -1, 0, -1, 1, 0, \dots]$$

$$y_i = X_i^T S = \langle X_i, S \rangle = (1 \cdot 0) + (-1 \cdot 1) + 0 + 0 + (-1 \cdot 1) + 0 = -2$$

$m = K \cdot s \log(d/s)$   
 $K \in [4, 20]$

# Examples CS

- single-pixel camera



- Hubble Space Telescope
- MRI (on kids)

Given matrix  $X$ , measurements  $y$   
 $\downarrow$  data  $\downarrow$   $\leftarrow$  prediction  
 How to recover  $S$ ?  
 $\downarrow$   $\downarrow$   $\leftarrow$  model

## Orthogonal Matching Pursuit OMP

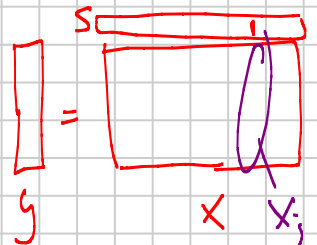
- choose column of  $X$  most useful

$$X_j = \arg \max_{X_j \in X} |\langle y, X_j \rangle|$$

$$y = \arg \min_{\gamma \in \mathbb{R}} \|y - X_j \gamma\| + \alpha \|\gamma\| \Rightarrow S_j = \gamma$$

$$\text{residual } r = y - X_j \gamma$$

$\gamma = \frac{X_j^T y}{\langle X_j, X_j \rangle}$



repeat until  $r$  all-zeros, or  $\|r\|$  small enough

$k$ th round

$x_{j_1}, x_{j_2}, \dots, x_{j_k}$

$$\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_k \end{pmatrix} = \underset{\gamma \in \mathbb{R}^k}{\text{argmin}} \left\| y - \begin{bmatrix} x_{j_1} & x_{j_2} & \dots & x_{j_k} \end{bmatrix} \gamma \right\|_2 + \alpha \|\gamma\|_1$$

$\gamma = (x_{j_1}^T x_{j_2} \dots x_{j_k}^T)^{-1} x^T y$