

# L25: the Perceptron Algorithm for separable linear classification

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FoDA

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# Linear Classification

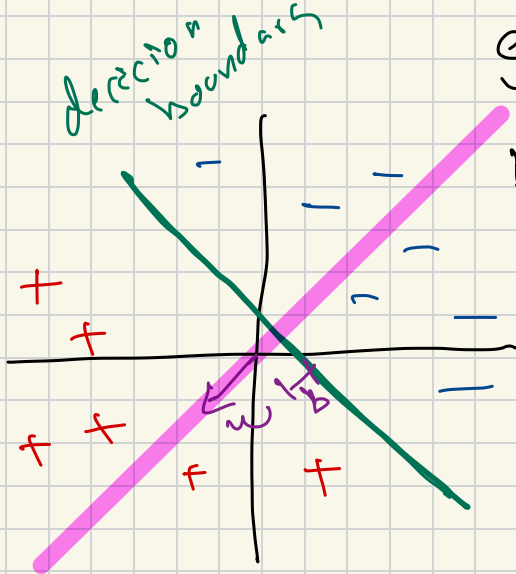
Input  $(X, y) \subset \mathbb{R}^d \times \{-1, +1\}$   
data points  $(x_i, y_i) \in \mathbb{R}^d \times \{-1, +1\}$  label

Output linear classifier  $(w, b) \in \mathbb{R}^d \times \mathbb{R}$

$$g_{w,b}(x) = \langle w, x \rangle + b \in \mathbb{R}$$

product  $x \Rightarrow +1$  if  $g_{w,b}(x) > 0$   
 $-1$  if  $g_{w,b}(x) < 0$

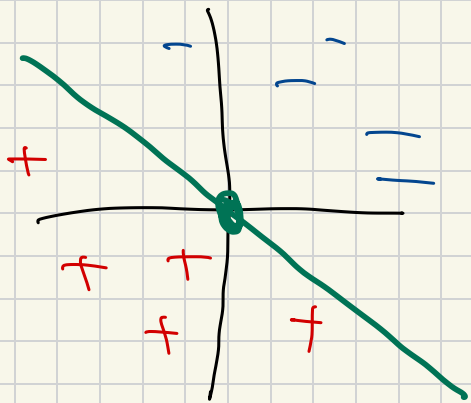
new data  $\rightarrow$   
no label



# Simplification for Perceptron

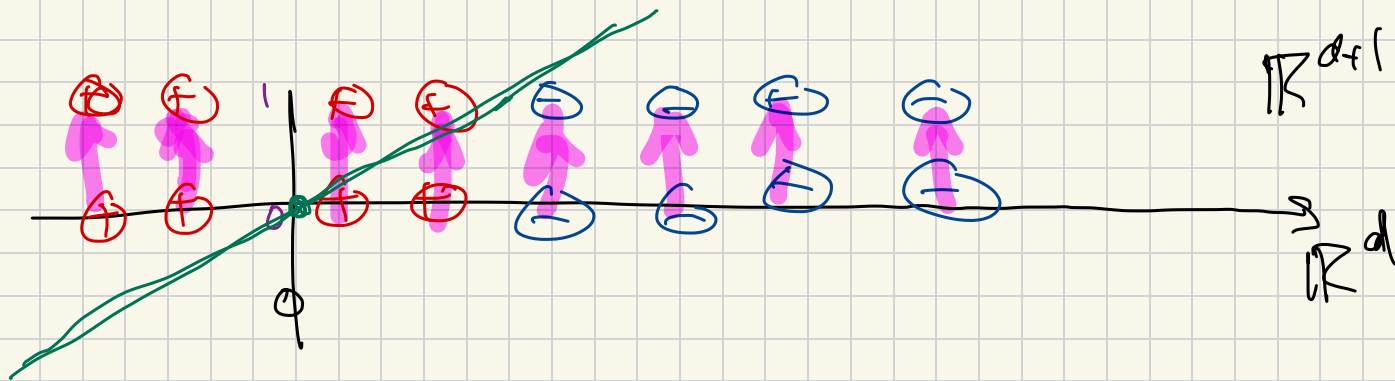
① Assume decision boundary passes through origin

$$g_w(x) = \langle x, w \rangle$$



convert  $x \rightarrow (1; x) \in \mathbb{R}^{d+1}$

$$(b, w) = (\alpha_0, \alpha_1, \dots, \alpha_d) \in \mathbb{R}^d$$



② Assume  $\forall x_i \in X \quad \|x_i\| \leq 1$

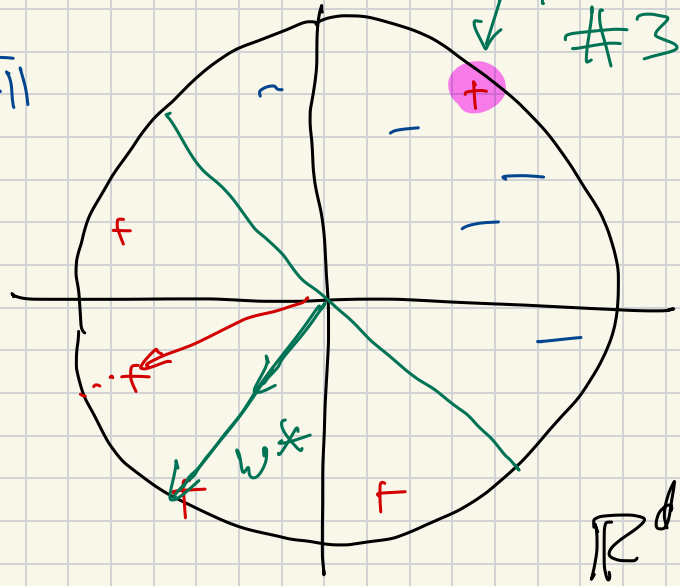
normalized

data

$$x_i \rightarrow \frac{x_i}{\|x_i\|}$$

or  $x_i \rightarrow \frac{x_i}{\max_{x \in X} \|x\|}$

$x_i$ 's violates  
Assume  
#3



③ Assume there exists  
a "perfect classifier"

$w^*$

so  $\forall (x_i, y_i) \in (X, Y)$

$$\text{sign}(g_{w^*}(x_i)) = y_i$$

# Perceptron Algorithm

0. Initialize : set  $w = \sum_i y_i x_i$  for any  $(x_i, y_i) \in \mathcal{X} \times \mathcal{Y}$

1. repeat

for any  $(x_i, y_i) \in \mathcal{X} \times \mathcal{Y}$  s.t.  $y_i \langle x_i, w \rangle < 0$   
misclassified

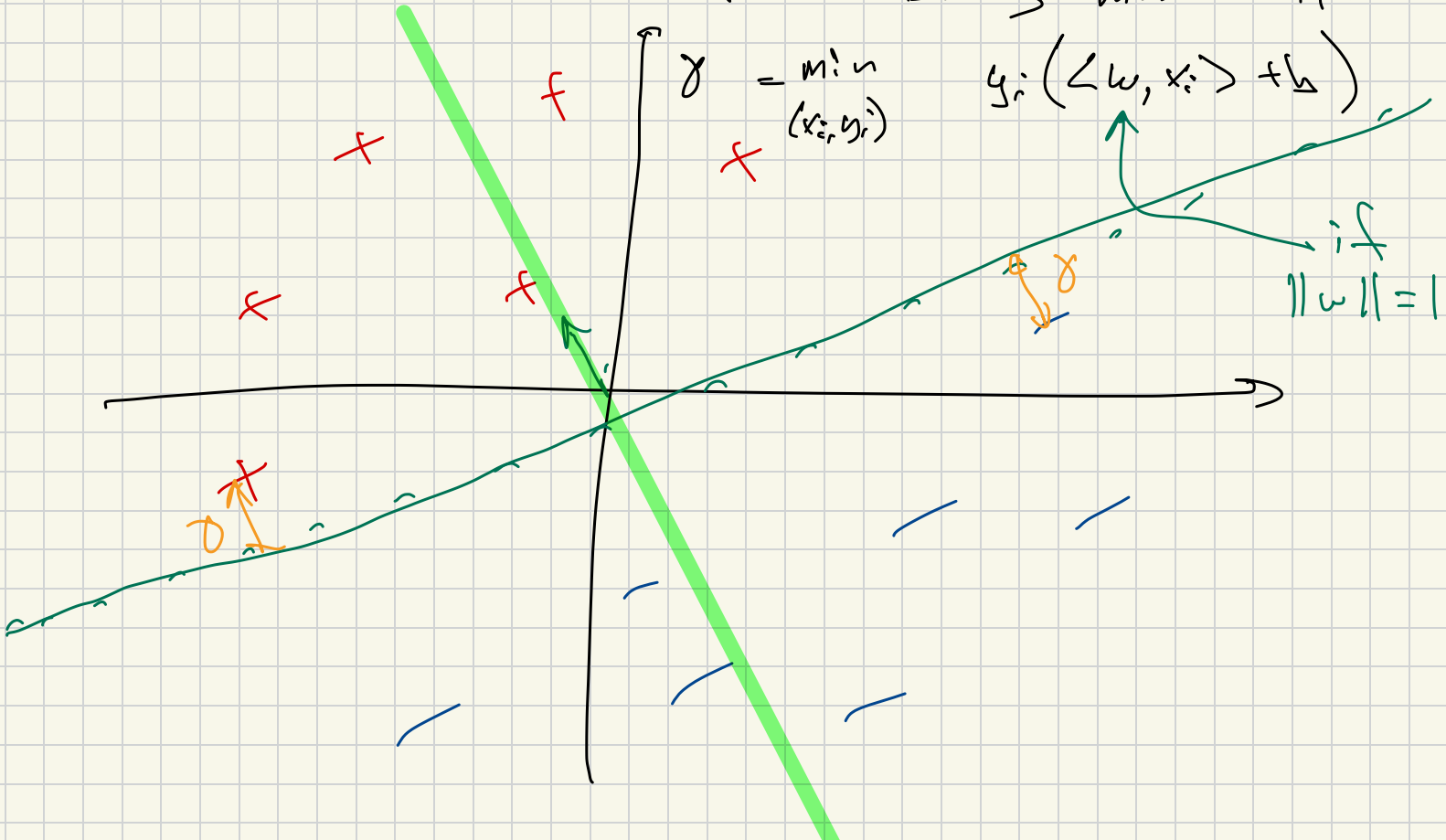
update  $w \leftarrow w + y_i x_i$

until ( no point or  $T$  steps )

2. return  $w \leftarrow \frac{w}{\|w\|}$  normalize  $w$

the Margin

$\gamma$  = how far is any data point from being misclassified



Max-Margin

Separator

$$w^*, b^* = \arg \max_{(w, b)}$$

$$\min_{(x_i, y_i)}$$

$$y_i: \text{Sw}_b(x_i)$$

margin

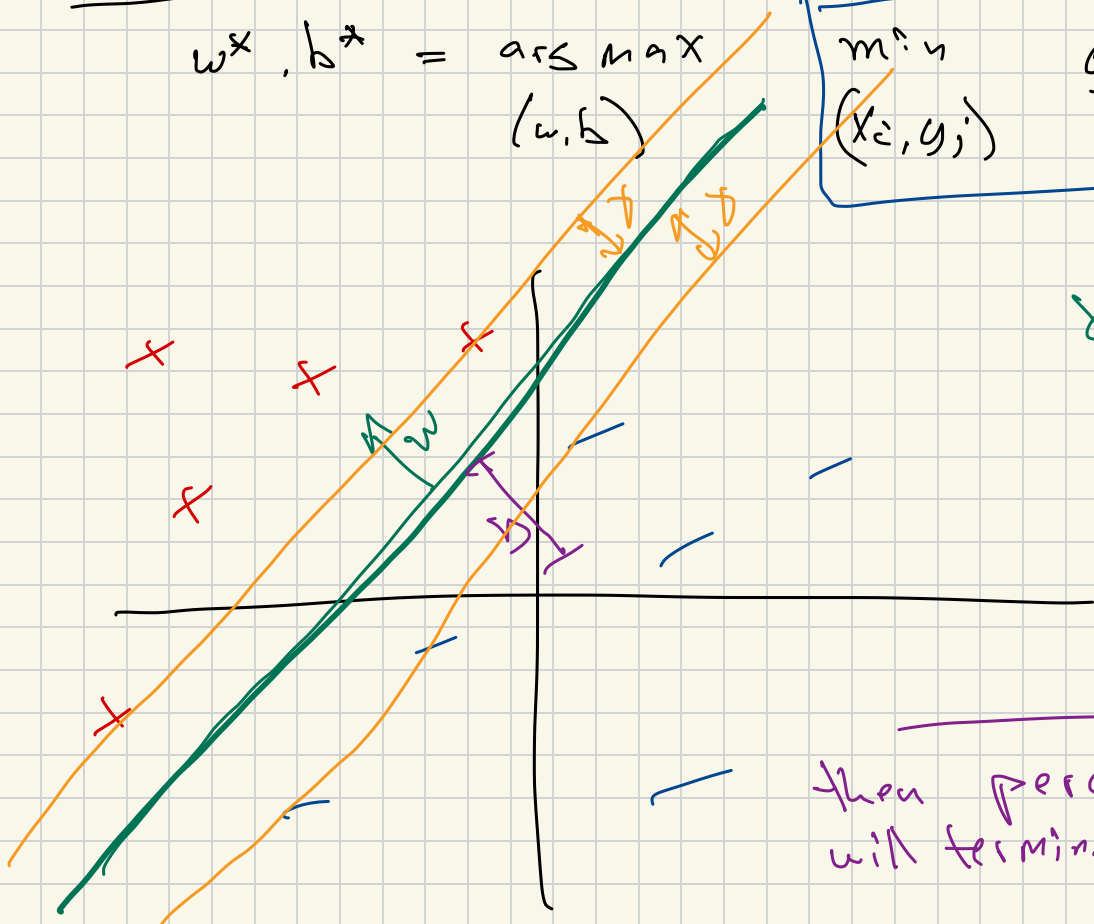
$$\gamma^* = \text{margin}$$

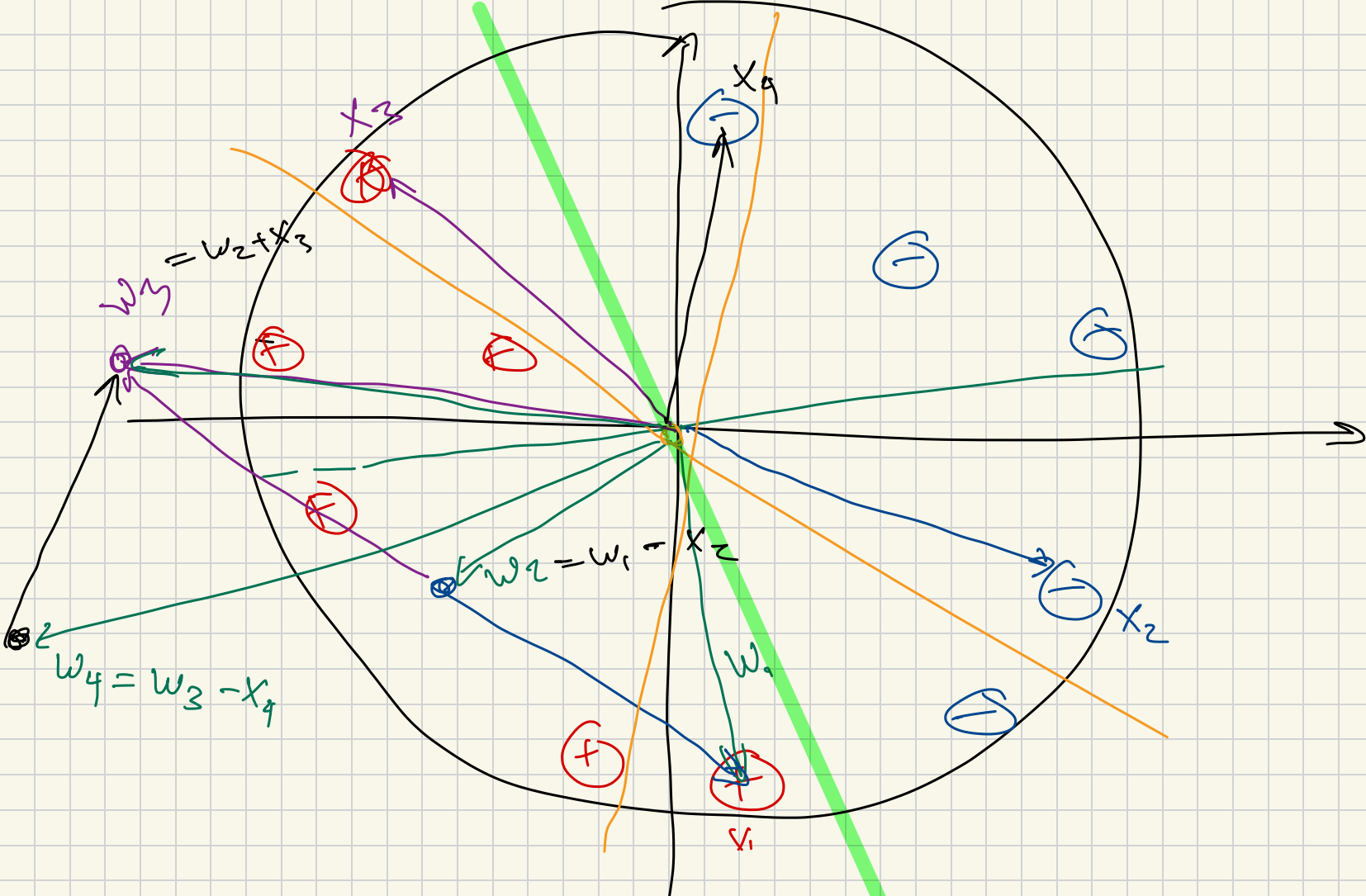
of the

max-margin classifier

$$\text{if } |x_i| \leq 1$$

then perceptron will terminate in  $(1/\gamma^*)^2$  steps.





Why does Perceptron work?

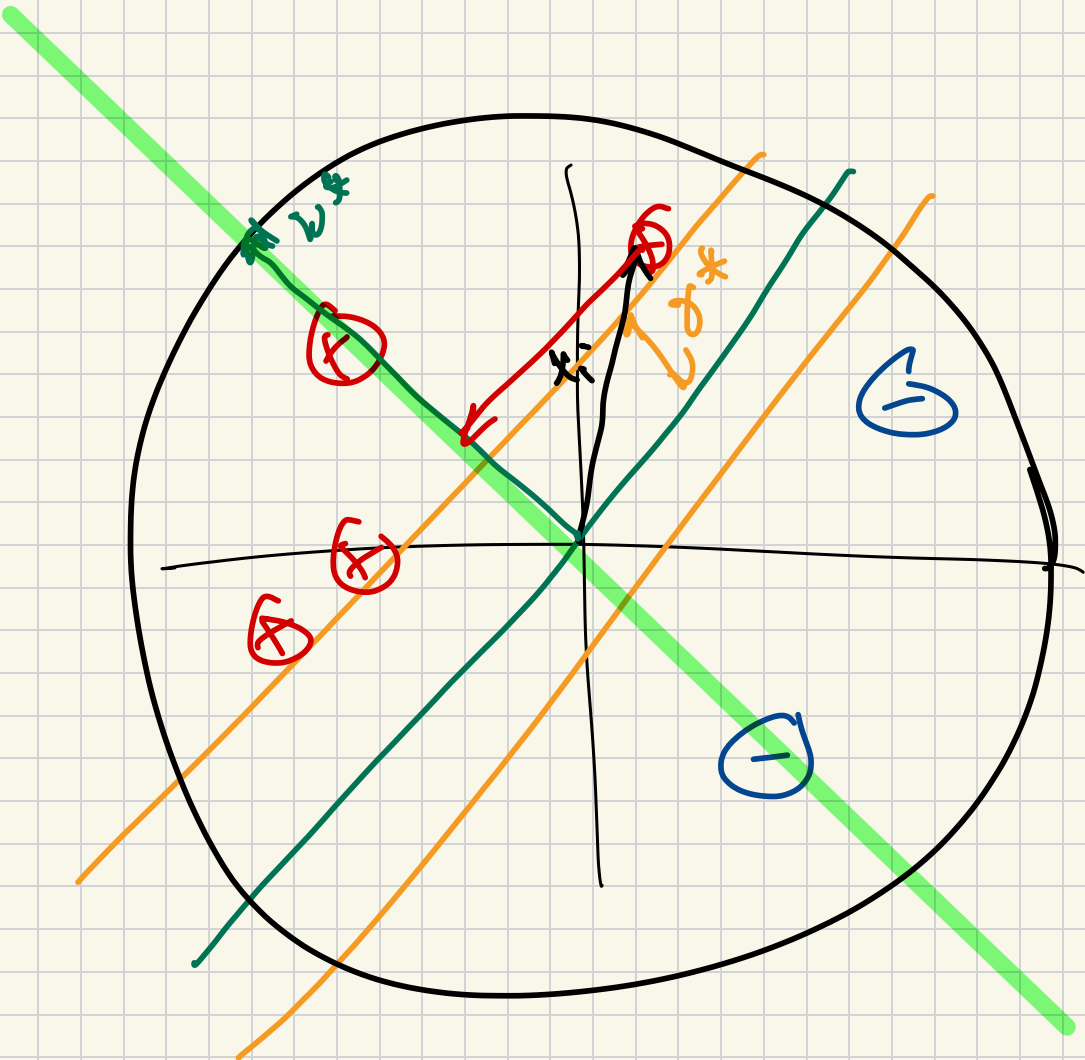
assuming #1, #2, #3  $\Rightarrow$  converge in  $\frac{1}{\gamma^*}$  steps  
no misclassified points.  
 $\gamma^* = \frac{\text{max margin}}{2}$

Analyze t steps of Perceptron

$$\textcircled{1} \quad \|w\|^2 \leq t \quad \Rightarrow \quad \|w\| \leq \sqrt{t}$$

$$\begin{aligned} \|w_{t+1}\|^2 &= \langle w_t + y_i x_i, w_t + y_i x_i \rangle = \langle w_t, w_t \rangle + (y_i)^2 \langle x_i, x_i \rangle + 2 y_i \langle w_t, x_i \rangle \\ &\leq \langle w_t, w_t \rangle + 1 + \underbrace{2 y_i \langle w_t, x_i \rangle}_{< 0} \\ &\Rightarrow \text{t steps } \|w_t\|^2 \leq t \end{aligned}$$

$$\textcircled{2} \quad \langle w_t, w^* \rangle > t \gamma^* \\ \langle w_t + y_i x_i, w^* \rangle = \langle w_t, w^* \rangle + y_i \langle x_i, w^* \rangle \geq \gamma^*$$



two properties

$$\textcircled{1} \quad \|w_t\| \leq \sqrt{t}$$

$$\textcircled{2} \quad \langle w_t, w^* \rangle > \gamma^* t$$

$$t \gamma^* < \langle w_t, w^* \rangle \leq \langle w_t, \frac{w_t}{\|w_t\|} \rangle \leq \|w_t\| \leq \sqrt{t}$$

$$t \gamma^* \leq \sqrt{t} \implies \gamma^* \leq \frac{\sqrt{t}}{t} = \frac{1}{\sqrt{t}}$$

$$t \leq \left( \frac{1}{\gamma^*} \right)^2$$