

FoDA - LI7

Gradient Descent

SGD, on data

Gradient Descent  $f: \mathbb{R}^d \rightarrow \mathbb{R}$

Goal:  $\underset{\alpha \in \mathbb{R}^d}{\operatorname{arg\,min}} f(\alpha)$

Input  $(X, y) = \{(x_1, y_1), (x_2, y_2), \dots (x_n, y_n)\} \subset \mathbb{R}^d \times \mathbb{R}$

"loss" function  $L((x, y), M_\alpha)$

$$f(\alpha) = L((x, y), M_\alpha) = SSE((x, y), M_\alpha)$$

$$= \sum_{(x_i, y_i) \in (X, y)} \underset{\alpha, x_i}{\langle M_\alpha(x_i) - y_i \rangle^2}$$

# Model $M_\alpha$ for polynomial regression

$$\mathbb{R}^d = \mathbb{R}$$

$$x_i \in \mathbb{R}$$

$$p=2$$

$$M_\alpha(x_i) = \langle \alpha, (1, x_i, x_i^2) \rangle = \sum_{j=0}^2 \alpha_j x_i^j$$

$\alpha = (\alpha_0, \alpha_1, \alpha_2) \in \mathbb{R}^3$

$n=1$   
single chart point

$$GD: \alpha = \alpha - \gamma \nabla f(\alpha)$$

$$\begin{aligned} j &= \{0, 1, 2\} \\ \frac{\partial}{\partial \alpha_j} f(\alpha) &= \frac{\partial}{\partial \alpha_j} (M_\alpha(x_i) - y_i)^2 = 2(M_\alpha(x_i) - y_i) \frac{\partial}{\partial \alpha_j} (M_\alpha(x_i) - y_i) \\ &= 2(M_\alpha(x_i) - y_i) \frac{\partial}{\partial \alpha_j} \left( \sum_{j=0}^2 \alpha_j x_i^j - y_i \right) \\ &= 2(M_\alpha(x_i) - y_i) x_i^j \end{aligned}$$

$$\frac{\partial}{\partial x_i} f(\alpha) = 2(M_\alpha(x_i) - y_1) x_i$$

$n=1$

$$\nabla f(\alpha) = \left( \frac{\partial}{\partial x_0} f(\alpha), \frac{\partial}{\partial x_1} f(\alpha), \frac{\partial}{\partial x_2} f(\alpha) \right)$$
$$= 2(M_\alpha(x_i) - y_1) \cdot (1, x_1, x_1^2)$$

LMS update rule, Widrow-Hoff update

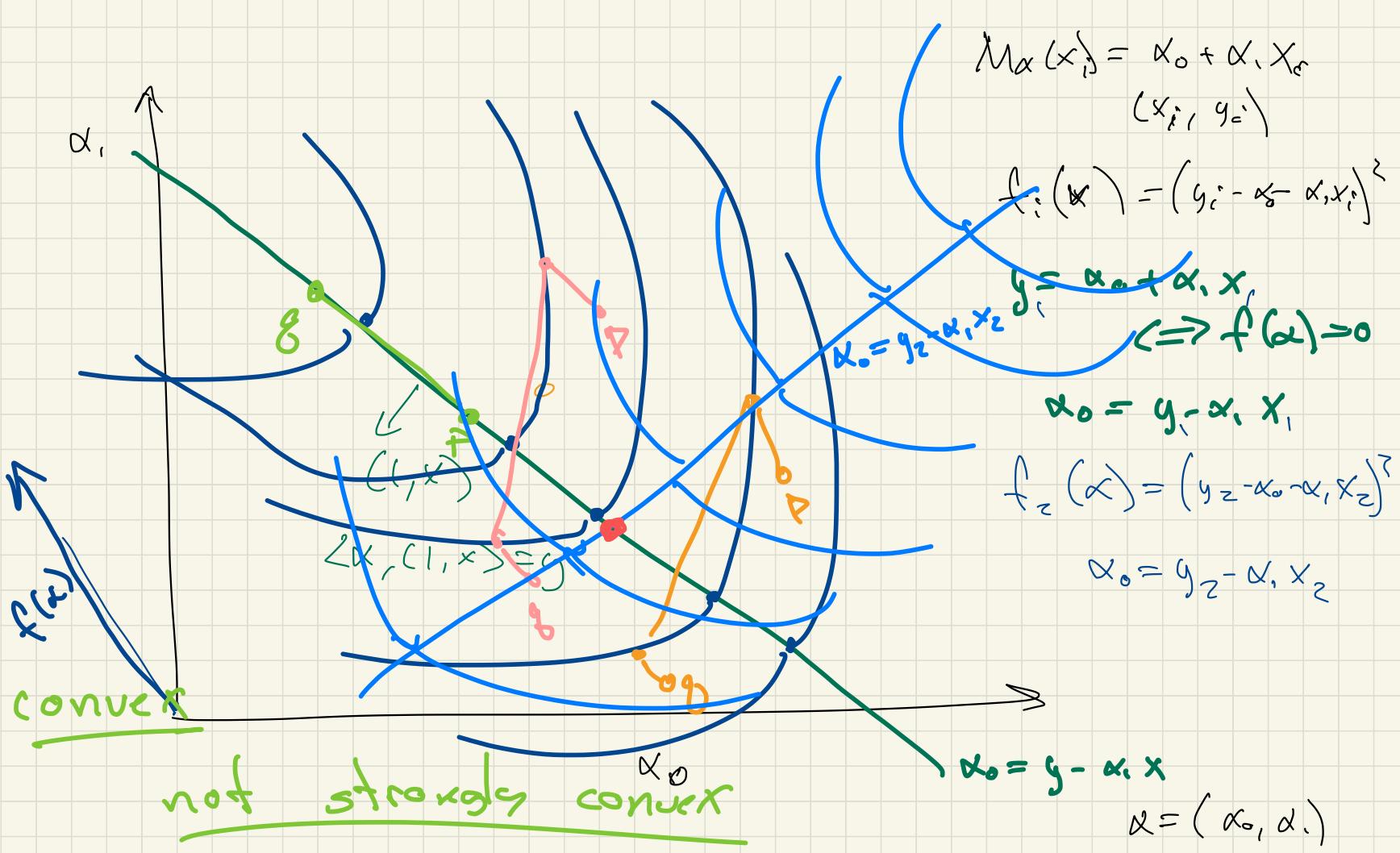
$$f(\alpha) = \sum_{i=1}^n f_i(\alpha)$$

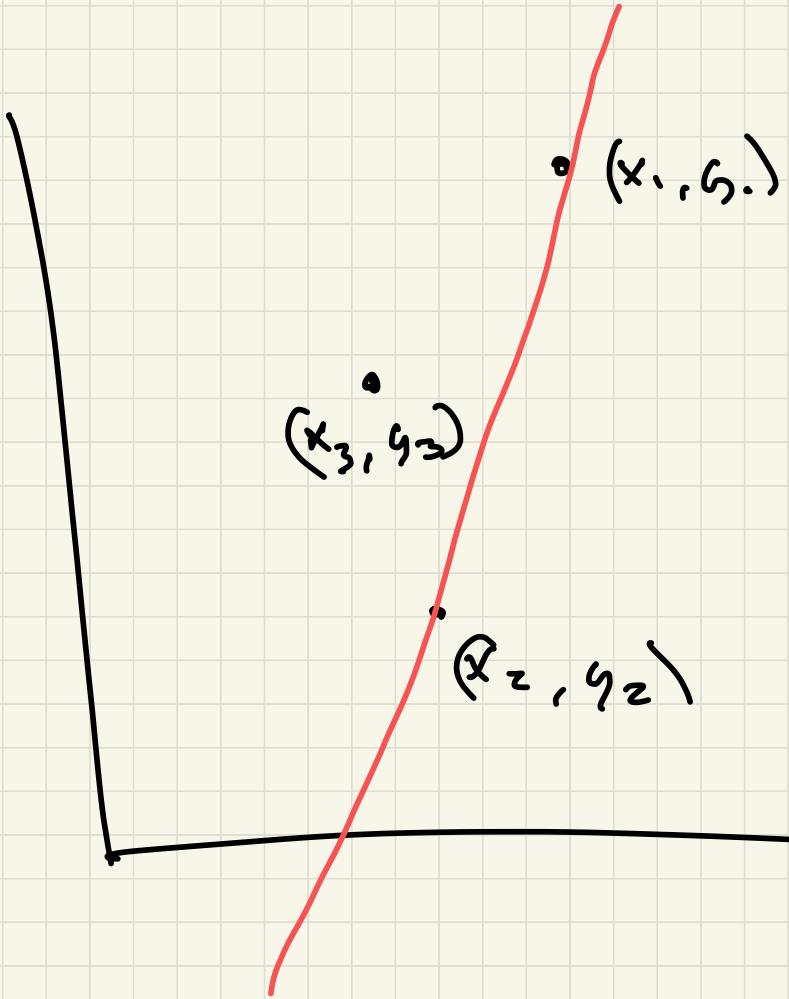
$n > 1$

decomposable function

$$\begin{aligned} f_i(\alpha) &= (\text{Max}(x_i) - g_i)^2 && \leftarrow \text{each } f_i: \\ &= (\alpha_0 + \alpha_1 x_i + \alpha_2 x_i^2 - g_i)^2 && (x_i, g_i) \end{aligned}$$

if each  $f_i$  is <sup>(strongly)</sup> convex, then  
 $f = \sum_i f_i$  is also <sup>(strongly)</sup> convex





if  $n \geq \# \text{ parameters}$

(not non-general case)

then  $f$  strongly

convex

$$f = \sum_{i=1}^n f_i$$

# Batch Gradient Descent ( $\text{Batch size} = n$ )

$$\alpha = \alpha - \gamma \nabla f(\alpha)$$

$$f = \sum_{i=1}^n f_i$$

$$\nabla f(\alpha) = \nabla \sum_{i=1}^n f_i(\alpha) = \sum_{i=1}^n \nabla f_i(\alpha)$$

$$\frac{\partial}{\partial \alpha_j} f(\alpha) = \sum_{i=1}^n \frac{\partial}{\partial \alpha_j} f_i(\alpha) = \sum_{i=1}^n (\text{M}_{\alpha}(x_i) - y_i) x_i^j$$

$$\nabla f(\alpha) = \sum_{i=1}^n (\text{M}_{\alpha}(x_i) - y_i) \boxed{\begin{pmatrix} 1, & x_i, & x_i^T \end{pmatrix}}$$

# Incremental Gradient Descent

$$\nabla f(\alpha) \approx \nabla f_i(\alpha) = 2(M_k(x_i) - y_i)(1, x_i, x_i^2)$$

$$x^{(0)} = \alpha^{\text{start}} ; i=1$$

repeat

$$\alpha^{(k+1)} = \alpha^{(k)} - \gamma_k \nabla f_i(\alpha^{(k)})$$

$O(1)$  time

to compute

$$z = (i + r) \bmod n$$

until  $\| \nabla f_i(\alpha^{(k)}) \| \leq T$

return  $\alpha^{(k)}$

faster average over  $B$  steps  
 $B = 10$ ?

# Stochastic Gradient Descent (SGD)

Init:  $\alpha^{(0)} = \alpha^{\text{start}}$

repeat

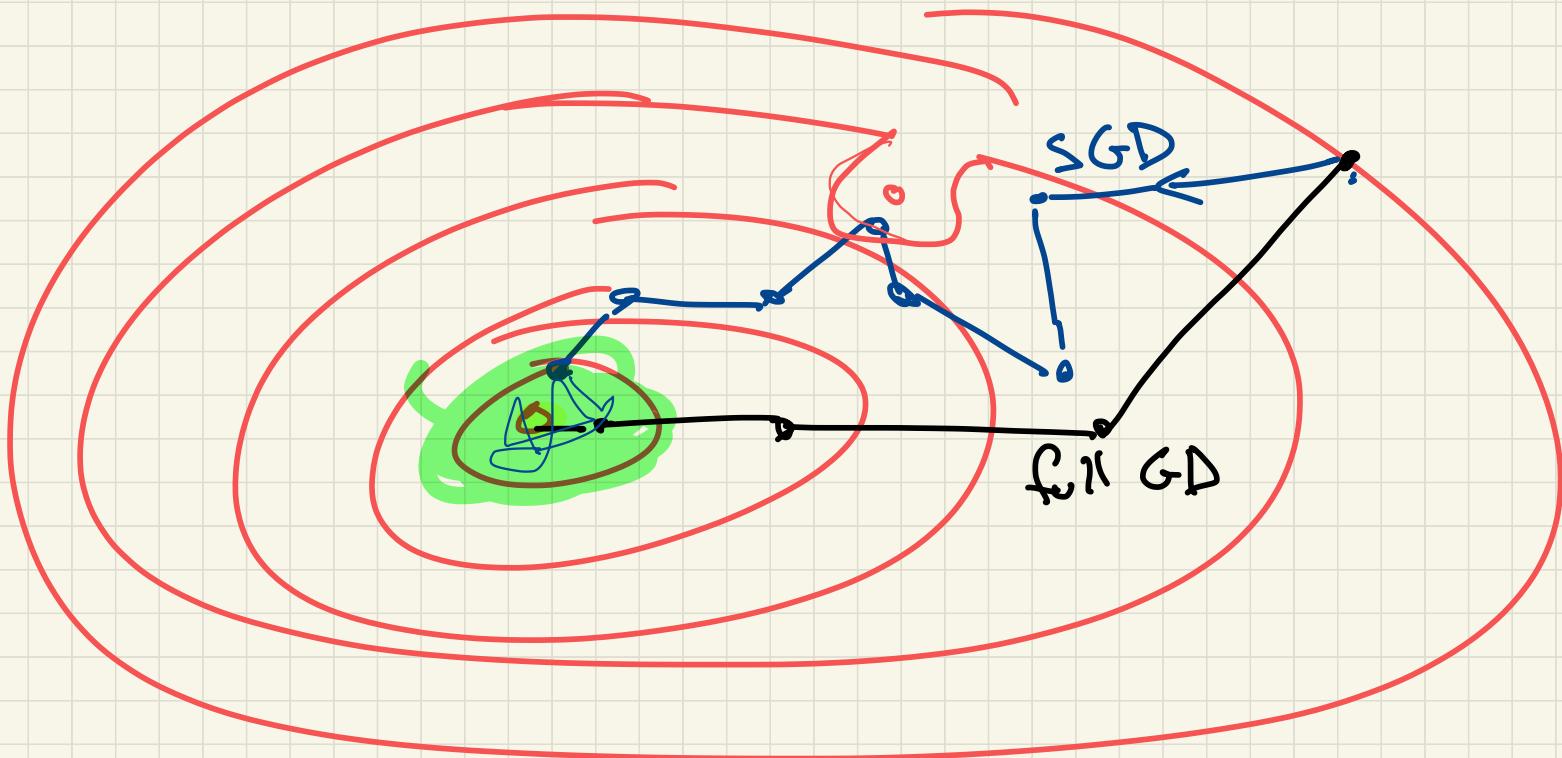
choose  $i \in [1 \dots n]$  at random

$$\alpha^{(t+1)} = \alpha^{(t)} - \gamma_k \nabla f_i(\alpha^{(k)})$$

until  $(\|\nabla f(\alpha^{(k)})\| \leq \epsilon)$

$t_{\text{average}}$

return  $\alpha^{(k)}$



SGD: more steps  
smaller steps | but each step is  
much, much faster