

You are trying to diagnose whether your computer is broken or not. On a given day, your computer's hidden state is either *broken* or *working*. Each day you make one of the following observations: *blue-screen*, *slow*, or *snappy*, depending on the state of your computer. You decide to use the following HMM to model your daily observations:

Initial Distribution		Transition Distribution			Emission Distribution		
State	$P(X_{\bullet})$	State	Next State	$P(X_{t+1} X_t)$	State	Observation	$P(O_t X_t)$
<i>working</i>	0.9	<i>working</i>	<i>working</i>	0.9	<i>working</i>	<i>snappy</i>	0.7
<i>broken</i>	0.1	<i>working</i>	<i>broken</i>	0.1	<i>working</i>	<i>slow</i>	0.2
		<i>broken</i>	<i>broken</i>	1.0	<i>working</i>	<i>blue-screen</i>	0.1
		<i>broken</i>	<i>working</i>	0.0	<i>broken</i>	<i>snappy</i>	0.1
					<i>broken</i>	<i>slow</i>	0.4
					<i>broken</i>	<i>blue-screen</i>	0.5

What is the most likely sequence of hidden states  $X_1, X_2, X_3$  given the observation sequence (*snappy*, *slow*, *blue-screen*)?

1. First, compute the  $m_1(x)$  values.
2. Next, compute the  $m_2(x)$  values.
3. Finally, compute the  $m_3(x)$  values.
4. Fill in the appropriate  $m_i$  values in the trellis below. Emphasize the back pointers by thickening the edges in the trellis from the final  $m_3$  values for both states *working* and *broken*.

