

# Tentative Syllabus

## Object-Oriented Programming for Interactive Systems

or

## Computing for Engineers

ME EN Special Topics 5960/6960-017

Course Instructor: Dr. David E. Johnson  
Instructor Webpage: [www.cs.utah.edu/~dejohnso](http://www.cs.utah.edu/~dejohnso)  
Office: WEB 2875, x5-1726  
Meeting Time: MWF 9:40-10:30  
Classroom: WEB L112

Textbook: TBA

**Course Description:** Many modern engineering systems incorporate computational elements, while other engineering systems needed to be validated through computational tools or through computer-aided data collection. This course is designed to provide a foundation in programming, software engineering, debugging, and using existing computational codes in the context of controlling physical equipment, gathering experimental data, and visualizing results. The course will be taught using the C++ programming language, which provides balance between access to physical devices and modern programming concepts. The course provides a level of programming proficiency to students planning on taking additional coursework with a programming emphasis or who might need custom computational applications in their research.

The course will use a mixture of short experimentation assignments (such as determining the result of certain programming constructs) and task-oriented programming assignments that demonstrate commonly used tools.

This is a combined 5xxx-6xxx level course. Students taking the 6xxx section will have small add-ons to homeworks and tests.

### *Proposed Schedule*

#### Basic Programming

##### Week 1

- Compiled languages/Imperative programming/Linear flow
- Variables – typing
- Control Flow – looping/conditionals
- Language Constructs Assignment

##### Week 2

- Functions
- Multiple files, header files
- Debugging
- Debugging a problem Assignment

## Object-Oriented programming

### Week 3

- Classes

- Constructors

- Methods

- Writing a vector class Assignment

## Communications

### Week 4

- Basic I/O

- Serial device I/O

- TCP/IP communication

- Controlling a robot arm over serial port Assignment

## GUI Toolkits

### Week 5

- Event-based programming

- Qt basics

- GUI layout

- Adding a GUI to robot control Assignment

## Template programming

### Week 6

- Basics of template programming/Using the STL for dynamic arrays

- Advanced STL structures

- Boost library

- Using STL Assignment

## Image Processing

### Week 7

- Introduction to openCV image processing library

- Programming as a pipe/filter paradigm/Basic image tools

- Capturing images from a camera

- Object Tracking Assignment

## Inheritance

### Week 8

- Inheritance

- Virtual functions

- Multiple inheritance

- Inheritance Assignment

## Simulation

### Week 9

- Intro to 3D graphics

- Microsoft Robotics Studio or Open Dynamics Engine

Collision Detection basics  
Simulation Assignment

Week 10

Simulation basics  
More on 3D graphics  
Generating quality images/videos  
Graphics Assignment

Visualization

Week 11

Intro to VTK  
Scalar fields  
Isosurfacing  
Visualization Assignment

Parallel Programming

Week 12

Threading  
Data safety in threads  
Threading architectures – vis loop, sim loop  
Threading Assignment

Scripting Languages

Week 13

Python basics  
Python class model  
Using Python with other packages  
Python Assignment