# Lecture 7: More on Graph Eigenvalues, and the Power Method

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#### **Abstract**

We will discuss a few basic facts about the *distribution* of eigenvalues of the adjacency matrix, and some applications. Then we discuss the question of computing the eigenvalues of a symmetric matrix.

#### 1 Eigenvalue distribution

Let us consider a d-regular graph G on n vertices. Its adjacency matrix  $A_G$  is an  $n \times n$  symmetric matrix, with all of its eigenvalues lying in [-d,d].

How are the eigenvalues *distributed* in the interval [-d,d]? Are there always many negative eigenvalues? What is the typical magnitude of the eigenvalues? The key to answering these questions is the simple fact that the trace of a matrix is the sum of its eigenvalues. Since all the diagonal entries of  $A_G$  are 0 (the graph has no self loops), we have that

The trace, denoted  $Tr(\cdot)$ , is defined to be the sum of the diagonal entries of a matrix.

$$Tr(A) = \sum_{i} \lambda_i = 0.$$

This means that the *average* of the eigenvalues is 0. Since we know that one of the eigenvalues is d, there have to exist eigenvalues that are < 0.

What is the typical *magnitude* of the eigenvalues? One way to measure this is to look at the average value of  $\lambda_i^2$ , i.e.,  $(1/n)\sum_i |\lambda_i|^2$ . To compute this, the idea is to come up with a matrix whose eigenvalues are  $\lambda_i^2$ , for  $i=1,\ldots,n$ , and compute its trace. We note that  $A_G^2$  is such a matrix.

What is the trace of  $A_G^2$ ? Let us consider the (i,i)th entry. It is precisely  $\langle A_i, A_i \rangle$ , where  $A_i$  is the ith row (or column) of  $A_G$ . For any i, this inner product is equal to  $\sum_j A_{ij}^2 = d$ , since precisely d of the entries are 1 and the rest are zero. Thus the trace is the sum over i of this quantity, which is nd. Thus, we have

$$\frac{1}{n}\sum_{i}\lambda_{i}^{2}=d$$

Thus, we expect the *typical* eigenvalue to have magnitude roughly  $\sqrt{d}$ . While this is not true of arbitrary graphs (see HW), it turns out that for *random* graphs of degree d, all the eigenvalues except the top one (which is d) turn out to lie between  $-2\sqrt{d}$  and  $2\sqrt{d}$ . In fact, they are *distributed* in a very nice way. See: *https://en.wikipedia.org/wiki/Wigner\_semicircle\_distribution*.

This is a special case of a more general phenomenon – for any polynomial p(), the eigenvalues of P(A) are  $p(\lambda_i)$ , where  $\lambda_i$  are the eigenvalues of A.

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1.1 EXERCISE. Show that we need not have eigenvalues that are  $\sim \sqrt{d}$ . We could have n/d eigenvalues that are  $\sim d$ , roughly.

1.1 Higher powers of the eigenvalues and walks

A nice combinatorial connection exists between powers of the adjacency matrix and the graph. Let us consider  $A_G^3$ , for concreteness.

What is the i,j'th entry of  $A_G^3$ ? If we write  $A = A_G$ , and  $B = A_G^2$ , we the quantity we are interested in, is

$$AB(i,j) = \sum_{k} A(i,k)B(k,j) = \sum_{k,l} A(i,k)A(k,l)A(l,j).$$

The sum is over all the possible choices of k and l. The term in the summation is non-zero precisely when ik, kl, lj are all edges in the graph. Thus the i, j'th entry of  $A_G^3$  measures exactly the number of walks of length 3 between i and j in the graph.

One consequence of this, is the fact that  $\operatorname{Tr}(A_G^3)$  is three times the number of *triangles* in the graph! Why? From the above, we know that the i,i'th entry of  $A_G^3$  is the number of walks of length-3 between i and itself. A length-3 walk between i is exactly the number of triangles with i as one of the vertices (note that there is no way we can have repeated vertices in a walk of length 3 from i to itself). Every traingle is counted three times when we take the trace – once for each of its end-points. Thus  $\operatorname{Tr}(A_G^3)$  is three times the number of triangles.

The walk interpretation of the adjacency matrix is useful – it lets us use properties of the graph to infer things about the distribution of eigenvalues and vice-versa.

### 2 Computing Eigenvalues

We have so far defined eigenvalues as the roots of the characteristic polynomial (the values  $\lambda$  such that  $\det(A - \lambda I) = 0$ ), and we iteratively defined  $\lambda_i$  as minimizers of the quadratic form  $x^T A x$  over unit vectors x.

How do we efficiently compute eigenvalues efficiently, given a matrix A. Suppose for now that A is an  $n \times n$  real, symmetric matrix, which implies it has n real eigenvalues. Call them  $\lambda_1, \ldots, \lambda_n$ , and let  $v_1, v_2, \ldots, v_n$  be the corresponding eigenvectors. Then, we saw that  $v_i$  form an orthonormal basis for  $\mathbb{R}^n$ . Furthermore, we saw that we can write

$$(1) \quad A = \sum_{i} \lambda_i v_i v_i^T.$$

## 2.1 Power Iteration

Suppose we start with some vector  $x \in \mathbb{R}^n$ , and compute

$$Ax$$
,  $A^2x$ ,  $A^3x$ , ...

Can we analyze what happens? It turns out that the right way to see what is going on is by writing x in terms of the eigenvectors. Suppose  $x = \sum_i \alpha_i v_i$ , for some  $\alpha_i$  (since the  $v_i$  form an orthonormal basis, there is a unique representation of x in this manner).

A walk is different from a simple path in that vertices can be repeated. For instance, we could have picked i - k - i - j, and that is a valid walk

Then, using (1), we observe that

$$Ax = \sum_{i} \alpha_{i} \lambda_{i} v_{i}$$

$$A^{2}x = \sum_{i} \alpha_{i} \lambda_{i}^{2} v_{i}$$

$$\vdots$$

$$A^{r}x = \sum_{i} \alpha_{i} \lambda_{i}^{r} v_{i}$$

Thus the coefficients of  $v_i$  evolve in a very clean way when we repeatedly multiply by A. Let us see a simple example. Suppose we have n=3, and suppose the eigenvalues are -1,1,2. Then, if we start with an x as above, we have  $A^rx = (-1)^r\alpha_1v_1 + \alpha_2v_2 + 2^r\alpha_3v_3$ . Now the crucial thing to observe is that the coefficient of  $v_3$  grows at a much faster rate than the coefficients of  $v_1$  and  $v_2$ . Suppose we started with all  $\alpha_i$  being equal to 1. Then, after 10 steps, the vector we have is  $v_1 + v_2 + 1024v_3$ , which when normalized is almost entirely aligned with  $v_3$ !

This is a general phenomenon. As long as we have one eigenvalue that is strictly larger than the others in magnitude, the term corresponding to that eigenvalue dominates, for large enough r.

**2.1 THEOREM.** Suppose the eigenvalues of A satisfy  $\max_{i < n} |\lambda_i| < (1 - \delta)|\lambda_n|$ , and let  $\epsilon \in (0,1)$  be the desired accuracy. Then for any vector x as above, consider  $A^r x$ , for

It is important to look at the magnitudes. Note also that sometimes the most negative eigenvalue could be the one with the largest magnitude.

$$r \geq \frac{\log D}{2\delta}$$
, where  $D = \frac{\sum_{i < n} \alpha_i^2}{\epsilon^2 \alpha_n^2}$ .

Then we have  $\|\frac{A^rx}{\|A^rx\|} - v_n\| < \epsilon$ .

*Proof.* The proof easily follows from what we observed earlier, and straightforward calculation. For any *r*, we have

$$A^r x = \sum_i \alpha_i \lambda_i^r v_i = \alpha_n \lambda_n^r \left( v_n + \sum_{i < n} \frac{\alpha_i}{\alpha_n} \left( \frac{\lambda_i}{\lambda_n} \right)^r v_i \right).$$

Let us consider the norm of the term in the summation. Since the  $v_i$  are all orthogonal, the squared-norm is

$$\sum_{i < n} \frac{\alpha_i^2}{\alpha_n^2} \left(\frac{\lambda_i}{\lambda_n}\right)^{2r} < \frac{\sum_{i < n} \alpha_i^2}{\alpha_n^2} (1 - \delta)^{\log D/\delta}.$$

Using the familiar inequality  $1 - \delta \le e^{-\delta}$  and simplifying, we get that the squared-norm is  $< \epsilon^2$ . Now, the vector in the summation is orthogonal to  $v_n$ , since the  $v_i$ 's are all orthogonal.

Thus, we have written  $A^r x = C(v_n + v_n^{\perp})$ , where  $v_n^{\perp}$  is orthogonal to  $v_n$  and has norm  $< \epsilon$ . This implies the theorem. (Details left as an exercise.)

Now consider the following algorithm: (called *power iteration*)

- 1. start with a random  $x \in \mathbb{R}^n$
- 2. repeat r times:  $x \leftarrow (Ax)/\|Ax\|$

What r should we choose? The theorem gives an r that works, but note that we do not know the values  $\alpha_i$  without knowing the  $v_i$  (which are what we are after in the first place!). Here's where the starting point being random comes in. With good probability (at least 99%), if x is chosen randomly (say, from the n dimensional Gaussian distribution), we will have  $\sum_i \alpha_i^2/\alpha_n^2 \leq O(n)$ , implying that choosing

If you do not see this immediately, it is a good exercise.

$$r = \frac{\log(n/\epsilon)}{\delta}$$

works with good probability.

The main factor determining the running time is  $(1/\delta)$ , which is often called the *eigenvalue gap*. Power iteration with a random starting point converges quickly if and only if the gap is large. In practice, the power method is a common tool in computing eigenvalues and eigenvectors.

What about matrices in which there is no (or very little) eigenvalue gap? We will see examples of this in the homework.

## 2.2 Beyond the top eigenvalue

What if we are interested in eigenvalues other than the *top* one? There are a couple of ways of extending the power method.

The natural one is to compute  $\lambda_n$  and  $v_n$  to a sufficiently high accuracy, and then *subtract it off* from the matrix. Since  $A = \sum_i \lambda_i v_i v_i^T$ , we will be left with  $\sum_{i < n} \lambda_i v_i v_i^T$  (plus a small noise, which we will need to keep track of).

The second way, which is often much better, is what is called the *block power method*. This works well if we are interested in the top-*k* eigenvalues in magnitude (for a small *k*).

The idea is to keep an  $n \times k$  matrix X (instead of a vector x), and repeatedly compute AX, followed by an orthonormalization step (instead of simply a normalization). It turns out that a similar analysis can be done, and now the convergence depends on the gap between the kth largest, and the (k+1)st largest eigenvalues.