# Algorithms, Geometry, and Optimization

#### (Lecture 21: Mon, Apr 1 2024)

Aditya Bhaskara

#### **Volume estimation**

**Problem.** Givien an *n*-dimensional convex body K (in the form of *membership* oracle), estimate vol(K).

Surprising: deterministic algorithms cannot do this!

*Theorem* (last lecture): For any deterministic algo that makes  $< 2^{n/2}$  queries, there is an instance where the estimation is off by  $2^{n/2}$ .

# **Randomized algorithms?**

Can obtain  $(1 + \epsilon)$  approximation with only polynomial  $(n, \frac{1}{\epsilon})$  many queries to the oracle.

Assumption. (technical) for some known R,

 $\mathcal{B} \subseteq K \subseteq R\mathcal{B}.$ 

(Runtime includes a  $\log R$  factor.)

#### Outline

**Claim 1.** Membership oracle  $\implies$  "sampling" oracle (poly time, obtain a random sample from *K*)

[*Spoiler:* done via random walks!]

Claim 2. This implies efficient volume estimation

One weird trick...

# Sampling & volume finding

Example: blindfold dartboards



What is the probability that dart lands on a black colored region?

## **Curse of dimensionality**

Volume of a cube / volume of "minimum enclosing" sphere is  $\exp(-n)$ 

 $\implies$  need to throw  $\exp(n)$  darts!

[Dyer, Frieze, Kannan] trick: define

$$K_j := \left(1 + rac{1}{n}
ight)^j \mathcal{B} \cap K$$

By definition,  $K_0 = \mathcal{B}, K_m = K$ , for  $m \approx n \log R$ 

### **DFK trick (contd.)**

Can write:

$$rac{\mathrm{vol}(K)}{\mathrm{vol}(K_0)} = rac{\mathrm{vol}(K_m)}{\mathrm{vol}(K_{m-1})} \cdot rac{\mathrm{vol}(K_{m-1})}{\mathrm{vol}(K_{m-2})} \cdots rac{\mathrm{vol}(K_1)}{\mathrm{vol}(K_0)}.$$

Key idea. Each of these terms is between [1, 3].

Thus, to estimate to error  $(1 + \gamma)$ , need  $\approx \frac{1}{\gamma^2}$  samples.

Choose  $\gamma = \frac{\epsilon}{2m}$  ( $\epsilon$  is desired overall accuracy)

#### **Recall outline**

**Claim 1.** Membership oracle  $\implies$  "sampling" oracle (poly time, obtain a random sample from *K*)

[Spoiler: done via random walks!]

Claim 2. This implies efficient volume estimation

One weird trick...

# **Sampling from membership**

How to create random sample from K?

- Start with any point  $x_0$
- Pick random point z in  $Ball(x_0, \delta)$  for some  $\delta > 0$
- If z is in K (membership), set  $x_1 = z$ , else  $x_1 = x_0$
- Repeat,  $x_2, x_3, \ldots$  for N = poly(n) steps

#### **Problems**

1. "Needles" -- can be inefficient -- but convex objects don't have too many!

- 2. What is the stationary distribution of this random walk?
- 3. How many iterations? main challenge